OPERATING INSTRUCTIONS

PicoFlow

FLOW MEASUREMENT AT LOW SOLIDS/AIR RATIOS

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1. System overview

A measuring point consists of the following components:

- Evaluation unit (MSE 300) in the DIN Rail housing or field housing
- Weld-on sensor socket with air purge connection
- Sensor
- C1- or C3-Box (optional)

The system can be equipped with up to three sensors. Depended on the number of sensors, different C-Boxes (C1, C3) should be use.

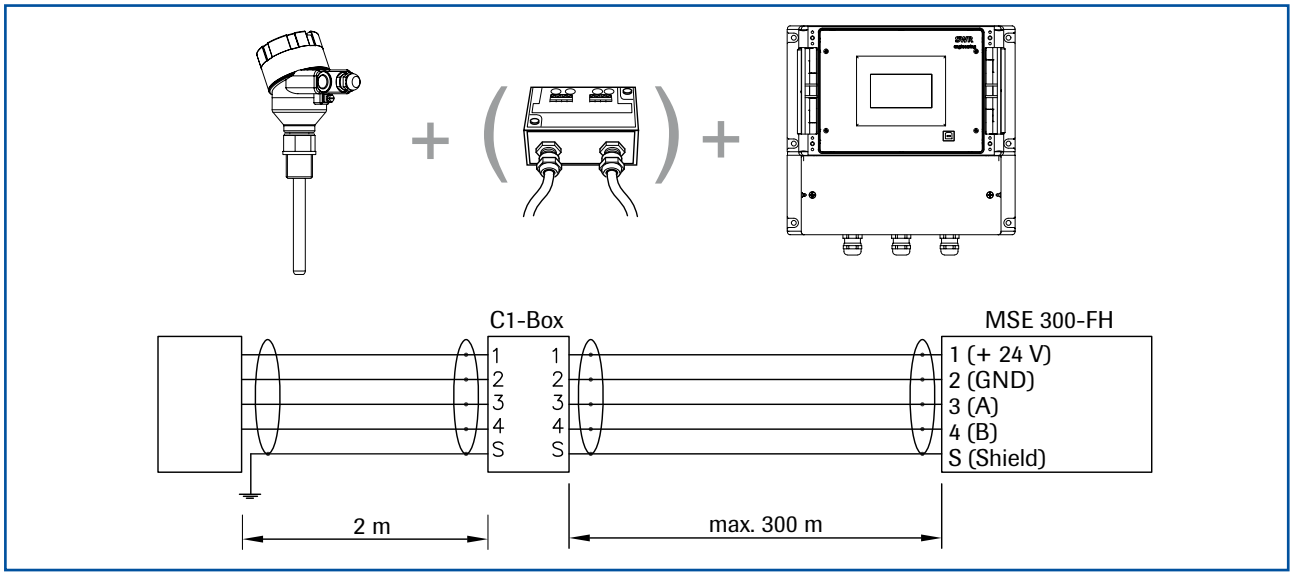


Fig. 1: Overview with C1-Box and MSE 300 in the field housing

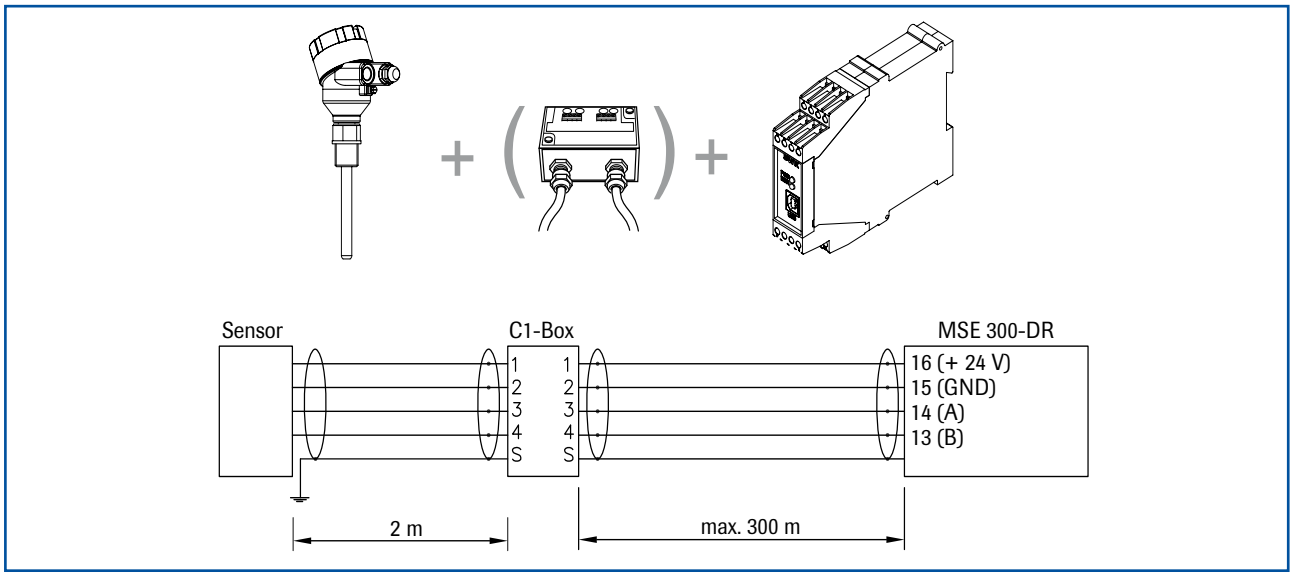


Fig. 2: Overview with C1-Box and MSE 300 in the DIN Rail housing

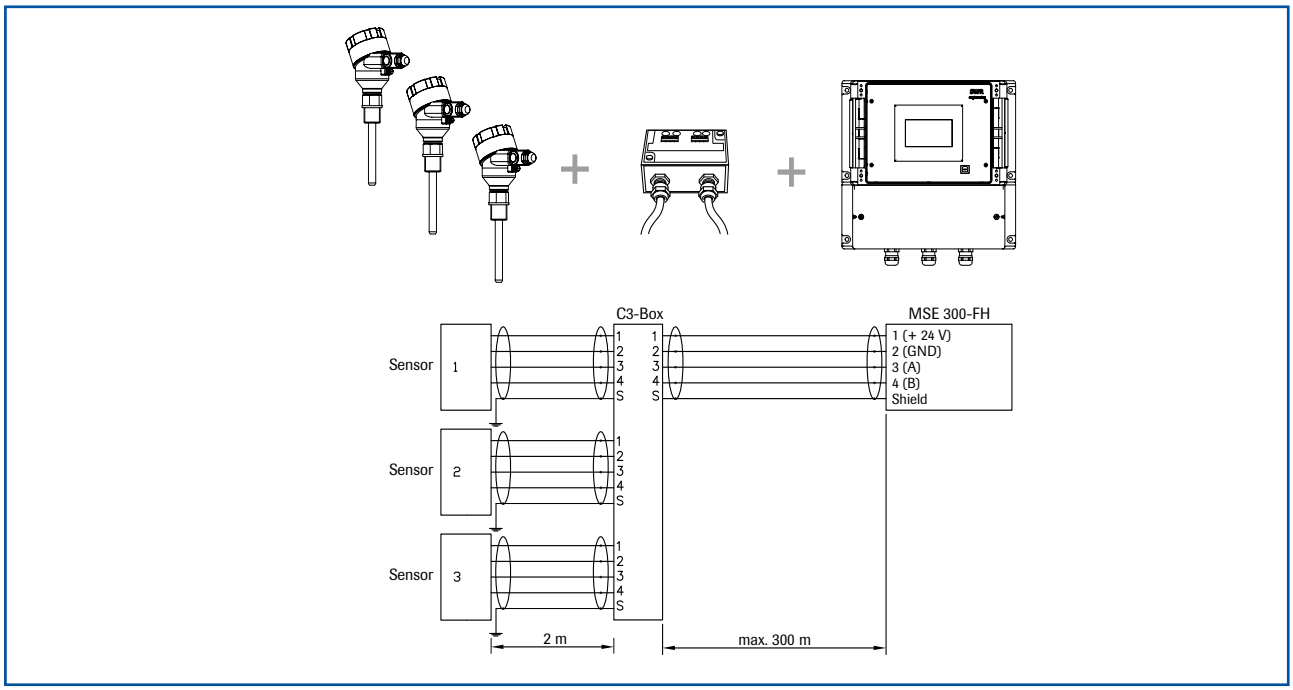


Fig. 3: Overview with C3-Box and MSE 300 in the field housing

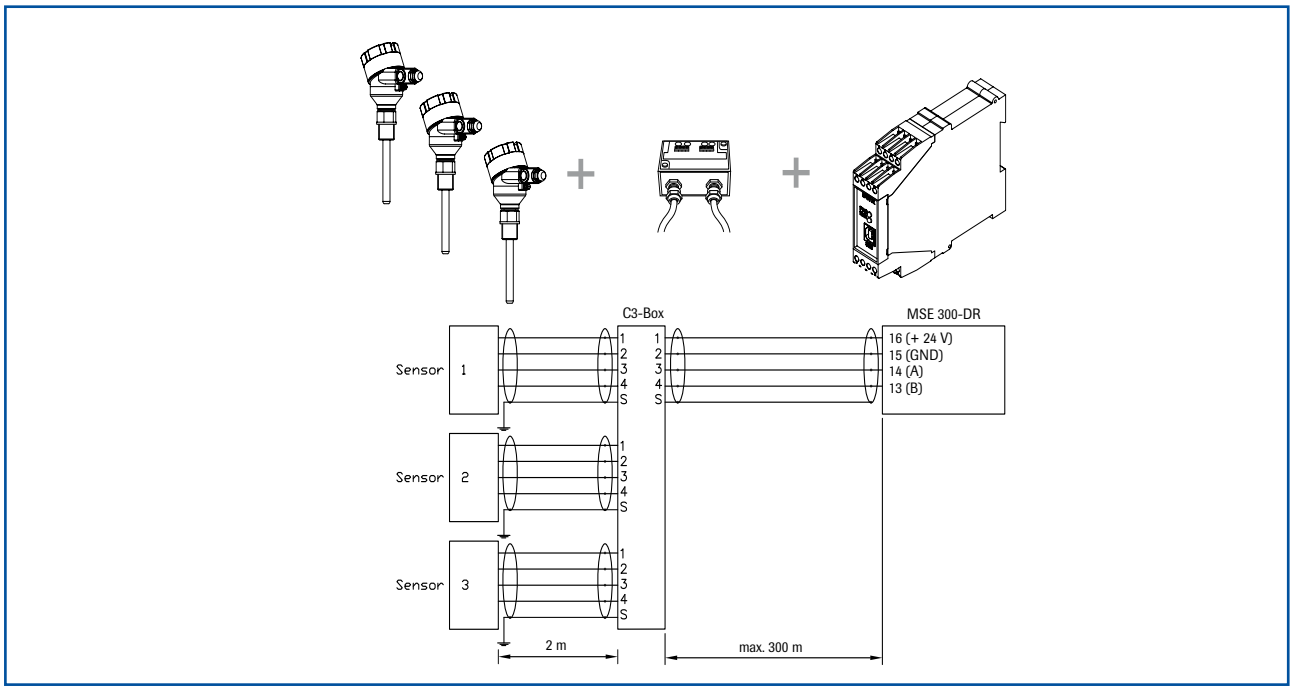
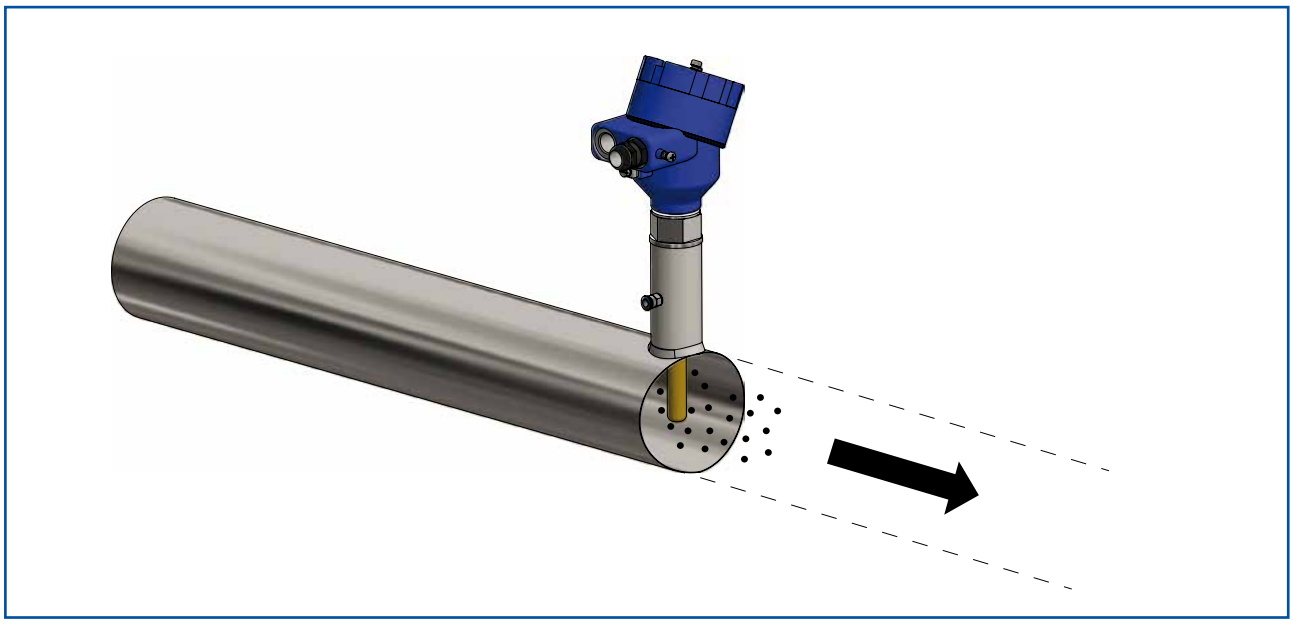


Fig. 4: Overview with C3-Box and MSE 300 in the DIN Rail housing

2. Function

- The PicoFlow is a measuring system which has been specially developed for measuring the quantity of pneumatically conveyed solids.
- It is used for very small solid / air ratios.
- The intrusive sensor probe is made of solid stainless steel and has an additional ceramic coating.
- The sensor works on electrodynamic principles. Each particle flowing past the probe generates a charge signal. The sum of all individual signals is temporally proportional to the quantity of solids.
- Each measurement point consists of a sensor and a evaluation unit.



3. Safety

The PicoFlow was designed, built and tested for safety and is shipped in this condition. Components within the supplied system could be hazardous if not unpacked, installed, connected and commissioned by authorised qualified persons. All operating instructions must be read, and understood, before handling the system. Failure to do so will cause the warranty to be revoked.

3.1 Normal use

- The measuring system may only be installed for measuring the low flow rate in metallic pipes.
- Only original spare parts and accessories of ENVEA Process must be used.

3.2 Identification of hazards

Possible hazards, when using the measuring system, are marked by the following symbols:

Warning!

- This symbolises a situation where personal safety is at risk if used in an improper manner.

Attention!

- This symbolises the possible damage to the system, if used in an improper manner.

3.3 Operational safety

- The measuring system must be installed by trained and authorised personnel only.
- In case of maintenance-work on the pipe or on components of the PicoFlow, make sure that the piping is in unpressurized condition.
- Switch off the power supply for all maintenance, cleaning or inspection works on the sensor or on components within the PicoFlow. Follow the notes of the chapter maintenance.
- Caution, if welding is required on the pipe, remove sensor.
- The components and electrical connections must be checked for damages regularly. If a damage is found, it is to be repaired before further operation of the instruments.

3.4 Technical statement

- The manufacturer reserves the right to change any technical data concerning technical developments, without prior notice. If any queries arise, ENVEA Process will be happy to inform customers of any possible changes made.

3.5 Reliability

For any additional information concerning product reliability, please contact ENVEA Process.

4. Mounting and installation

4.1 Delivery range:

- Evaluation unit (MSE 300) in the DIN Rail housing or field housing
- Weld-on sensor socket with air purge connection
- Sensor
- Operating instructions
- C1- or C3-Box (optional)

4.2 Auxiliary

- Drill Ø 27 mm for steel
- 36 mm open-end spanner for sensor-hexagon
- approved tools for the electric connection

4.3 Mounting of the sensor

Proceed as follows to install the sensor:

- Decide on the installation position on the pipe. It should be installed from the top on horizontal or angled pipelines.
- The probe length should be at least half of the diameter. The maximum probe length is 450 mm.
- If required, up to three sensors can be installed in one line.
  - In a two-sensor application, the sensors are used in a 90° offset.
  - In a three-sensor application, the sensors are used in a 120° offset.
- The distances apply to vertical and horizontal installations.
- Ensure that the measurement point is an adequate distance from valves, manifolds, blowers and bucket wheel feeders and other measurement ports such as those for pressure and temperature sensors, etc. (Fig. 6).

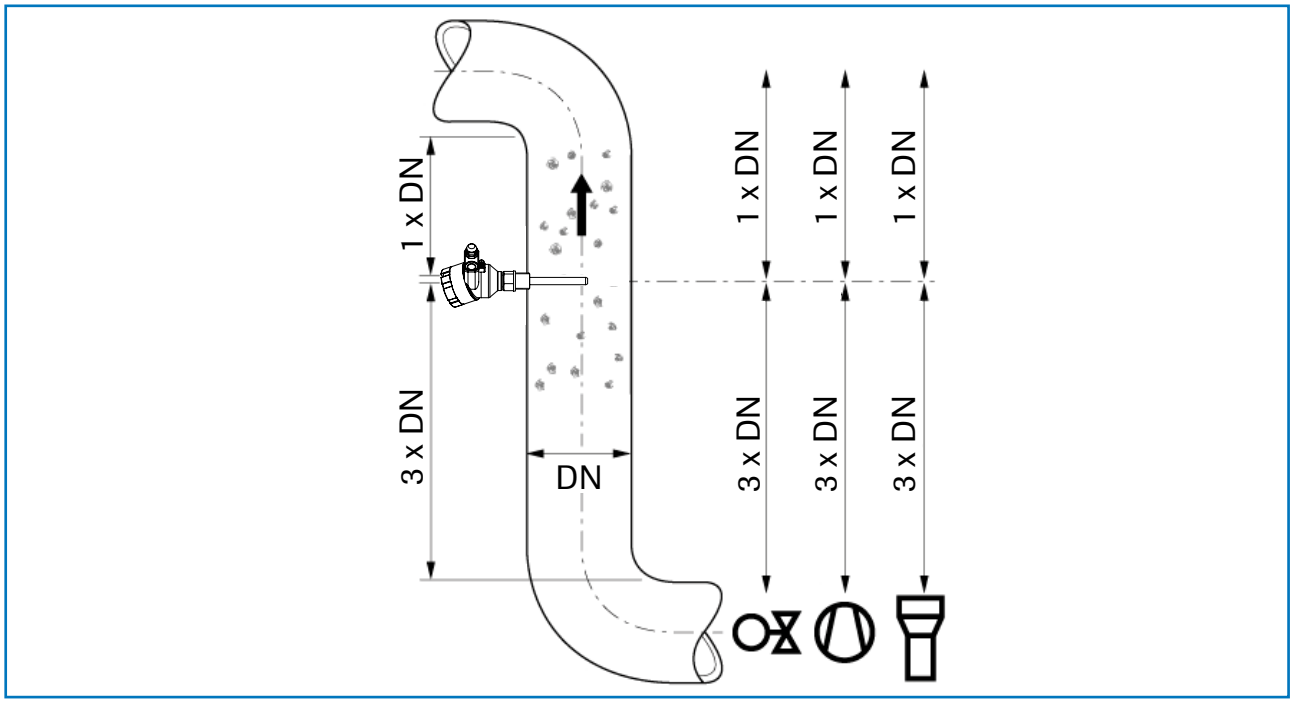


Fig. 6: Recommended distances to bends (DN = duct diameter) and built-ins

- Weld the sensor accommodation to the duct. **The plastic inlay and the air connection must be removed before welding.**
- Drill the hole of 27 mm diameter through sensor accommodation. Ensure that the borehole is not angled so that the sensor can be installed precisely at a later stage.

Attention!

- After drilling it is essential to check whether the drill bit has caused any burr on the borehole edges. Any burr on the pipe must be removed using a suitable tool. If the burr is not removed it may affect the sensor‘s calibration.
- If the sensor will not installed immediately, the socket could be closed by an 1” end cap.
- The sensor is delivered with a probe length adapted to the pipe diameter.
- The sensor is then inserted through the sensor socket and fixed.
- The purge air connected via an M5-connection nipple.

The following condition must be fulfilled for the purge air:

- The purge air must be continuous, no pulses.
- The pressure should be minimum 0.5 bar over the pressure in the transmission pipeline.
- In principle, the pressure strength should be selected in such a way that no material can deposit between the sensor rod and the inner wall of the nozzle.
- The flushing air must be dry, free of oil and environmental conditions.

4.4 Mounting the Evaluation unit

The evaluation unit can be installed at a maximum distance of 300 m from the sensor. A cable of type “Ölflex Classic 110 CY” is recommended. The cable should be four wired, twisted and shielded. A minimum cable cross-section of 0.75 mm² should be observed. For distances more than 150 m the cable cross-section should be adjusted.

The housing is prepared for DIN Rail mounting according to DIN EN 60715 TH35.

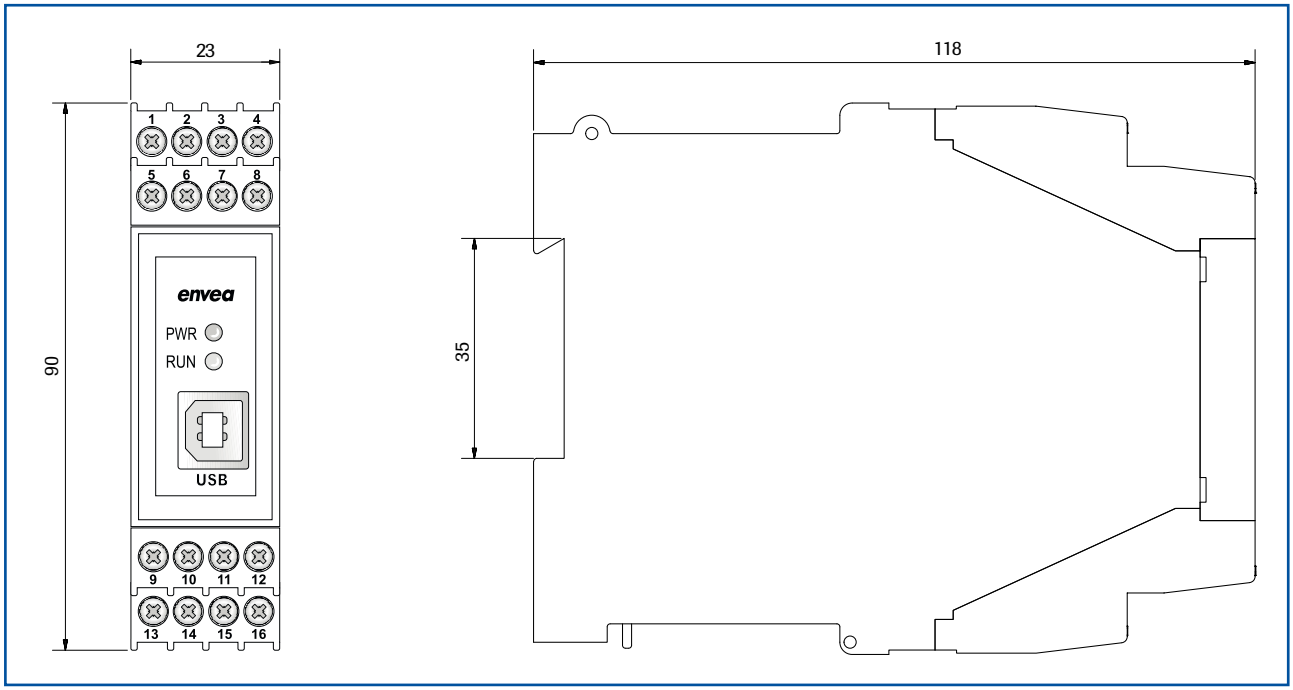


Fig. 7: Dimension of the MSE 300-DR

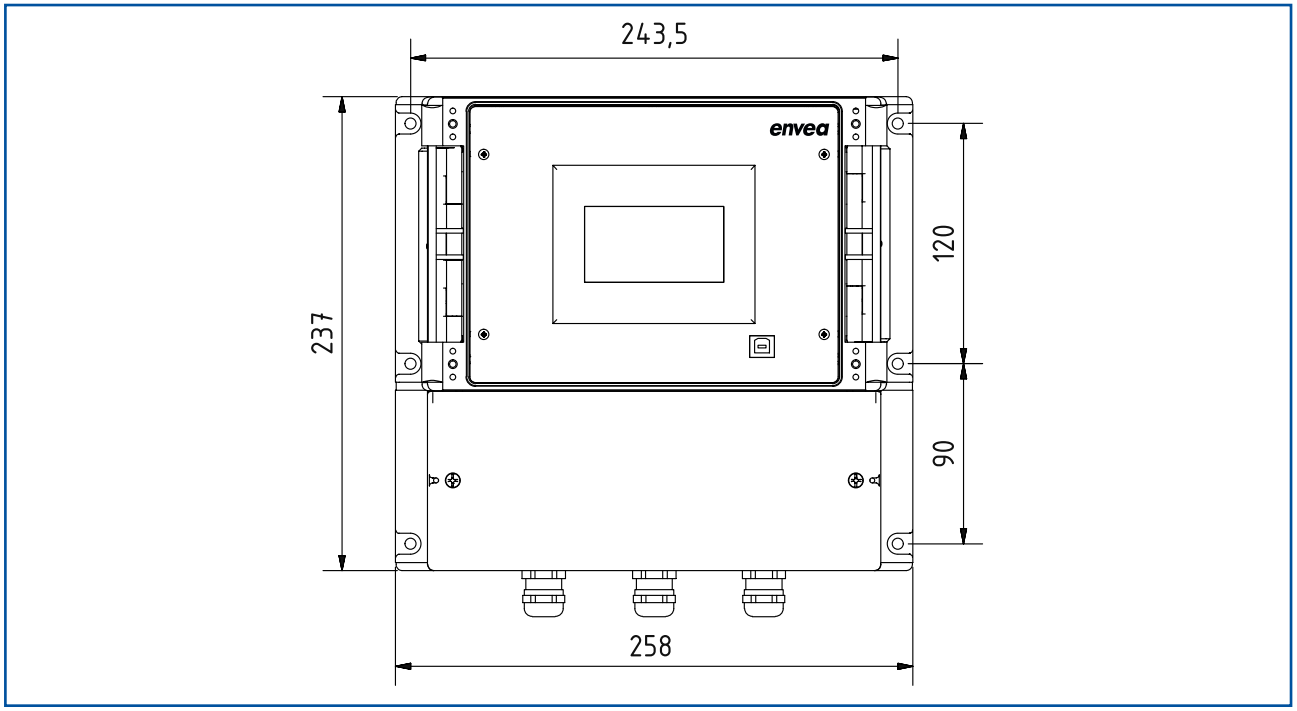


Fig. 8: Dimension of the MSE 300-FH (front)

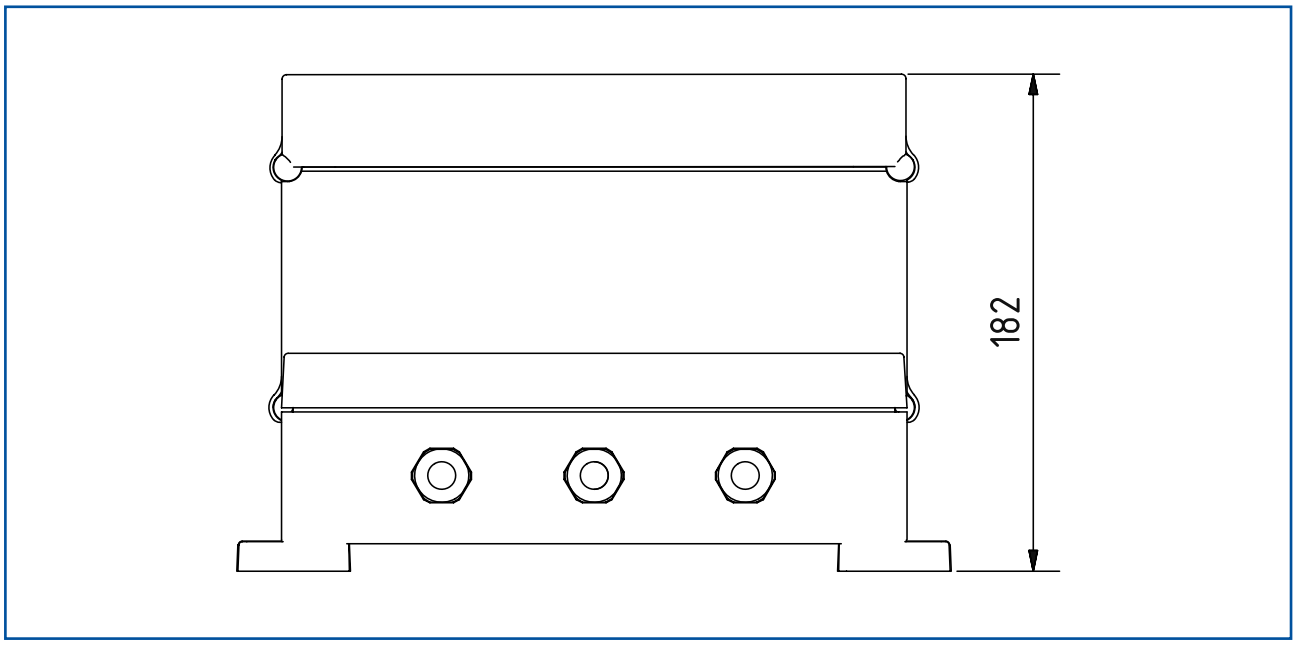


Fig. 9: Dimension of the MSE 300-FH (side view)

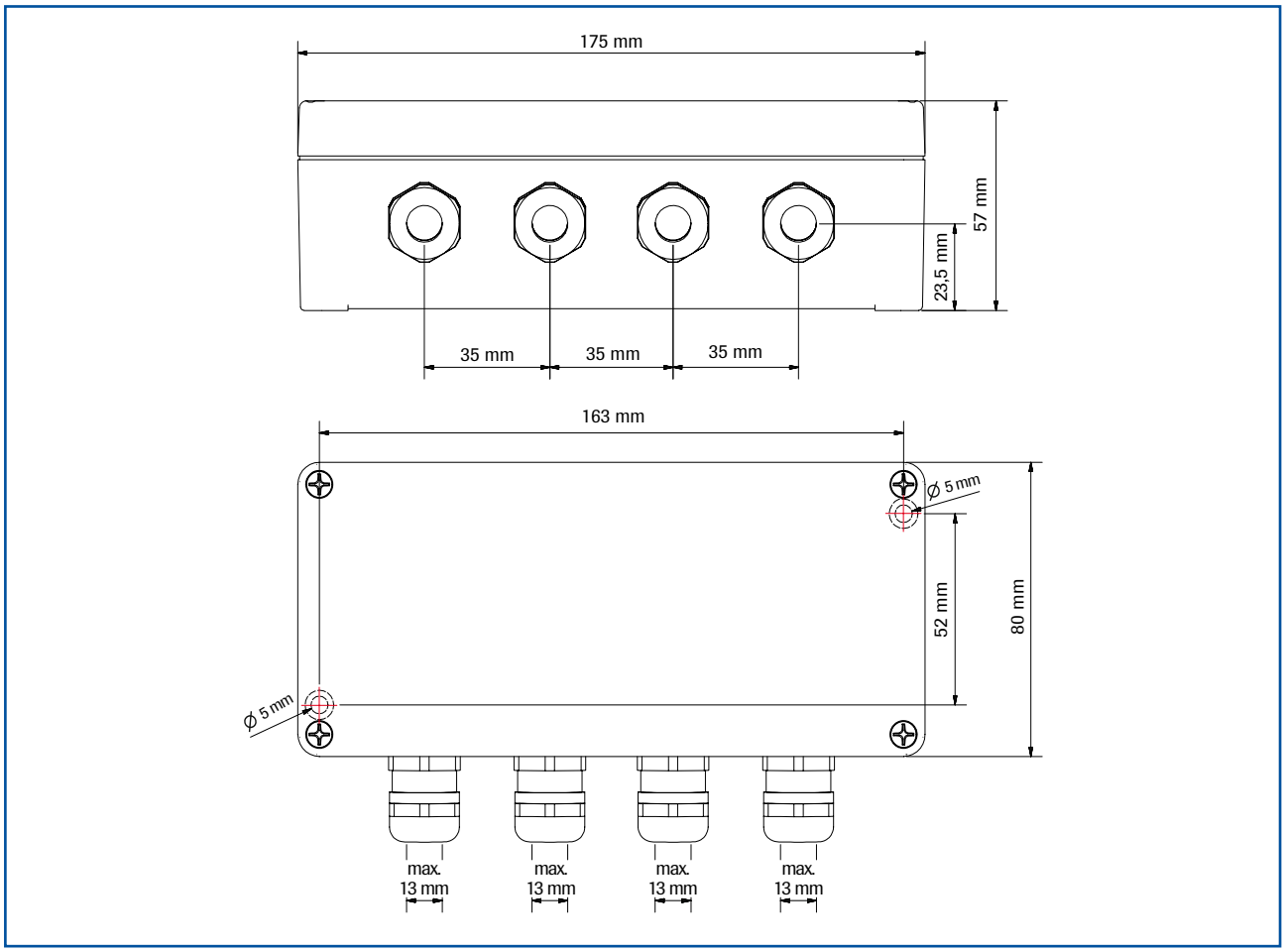


Fig. 10: Dimension of the C3-Box

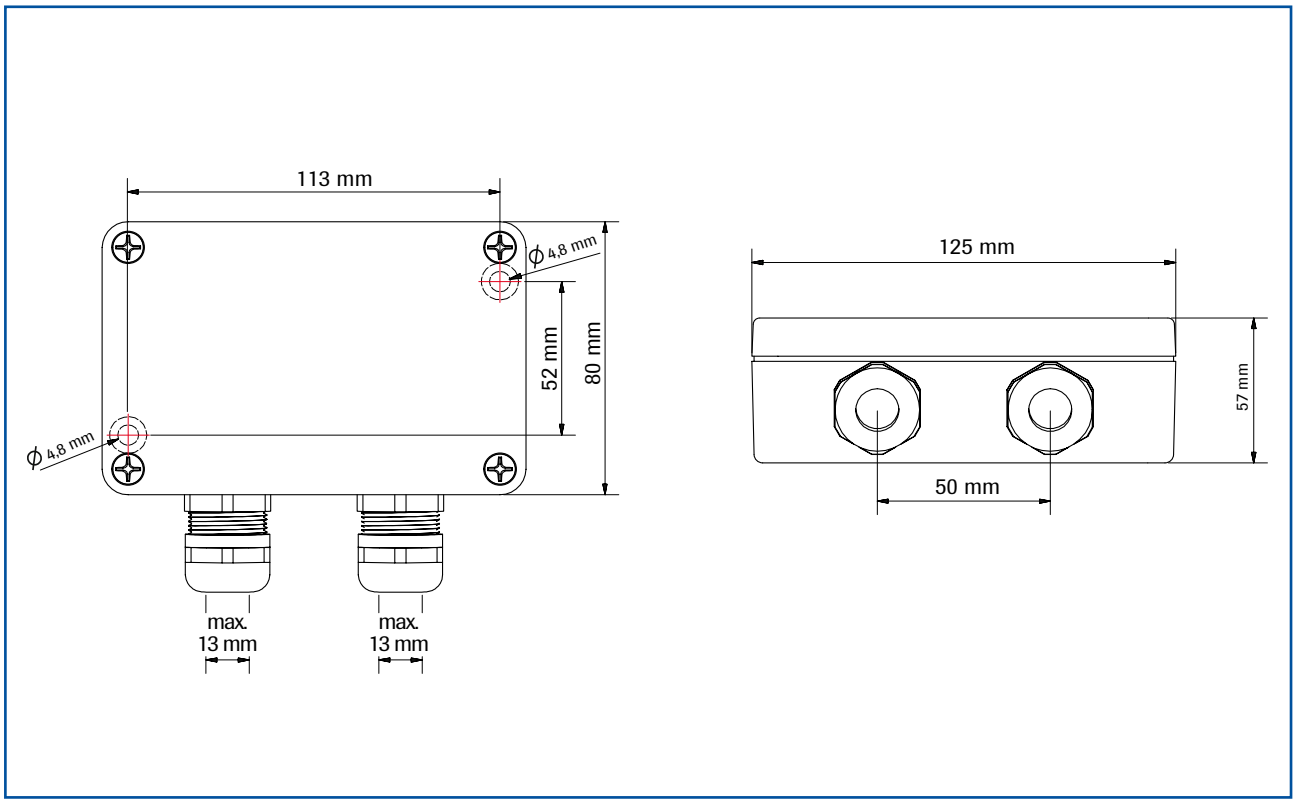


Fig. 11: Dimension of the C1-Box

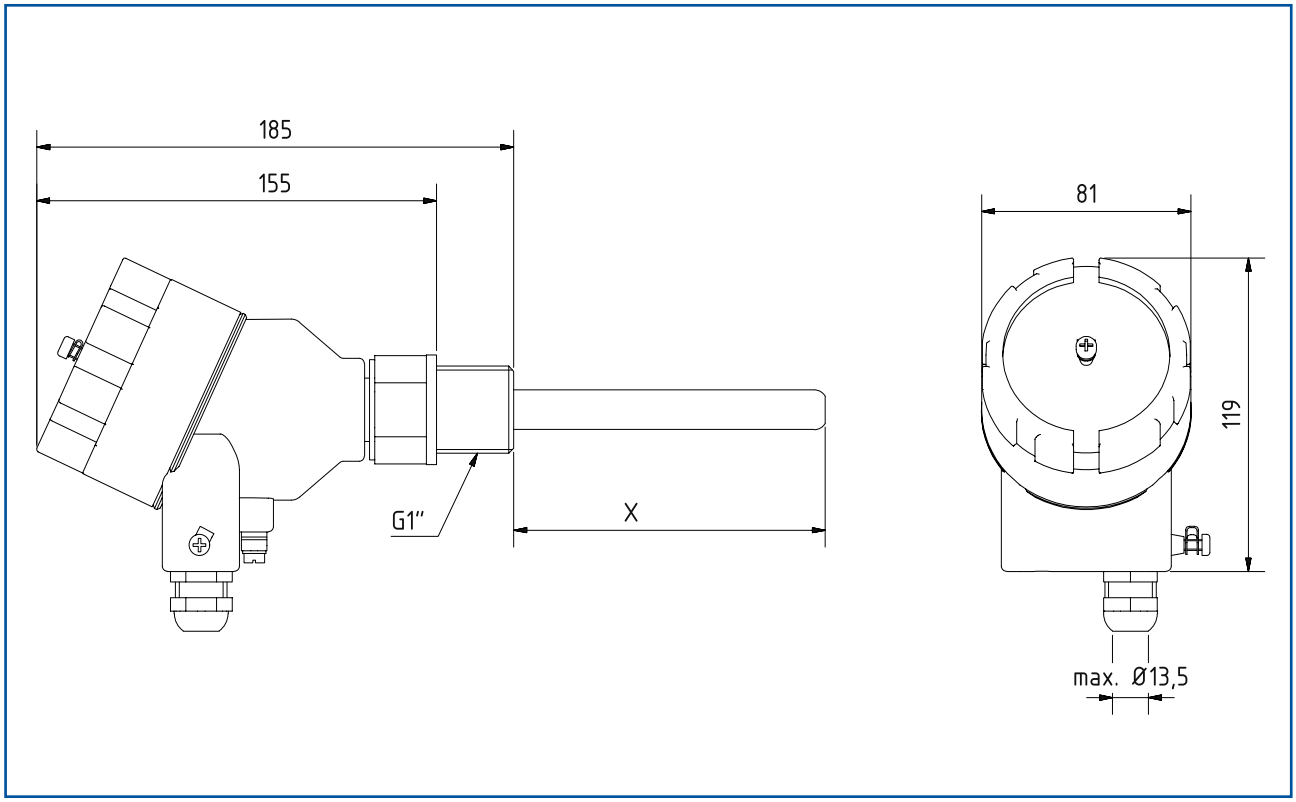


Fig. 12: Dimension of the PicoFlow sensor

4.5 Use in Ex hazardous areas

Marking DustEx: **II 1/2D Ex ia/tb IIIC Tx* °C Da/Db**

***-electronics / enclosure**

Zone 20: -20 °C ≤ $T_{process}$ ≤ 250 °C

Zone 21: -20 °C ≤ T_{amb} ≤ 60 °C

- Equipment group: 2
- Equipment category: 1/2 Electrode zone 20 / enclosure zone 21
- For explosive mixtures of air and combustible dusts
- IP-code 68
- Permitted process temperature -20 to 250 °C
- Up to process temperatures of 120 °C, the maximum surface temperature of the electronic enclosure is 120 °C. In case of higher process temperatures. At higher process temperatures the allowable surface temperature is determined by the process temperature.

Marking GasEx: **II 1/2G Ex ia/d IIC T4* Ga/Gb**

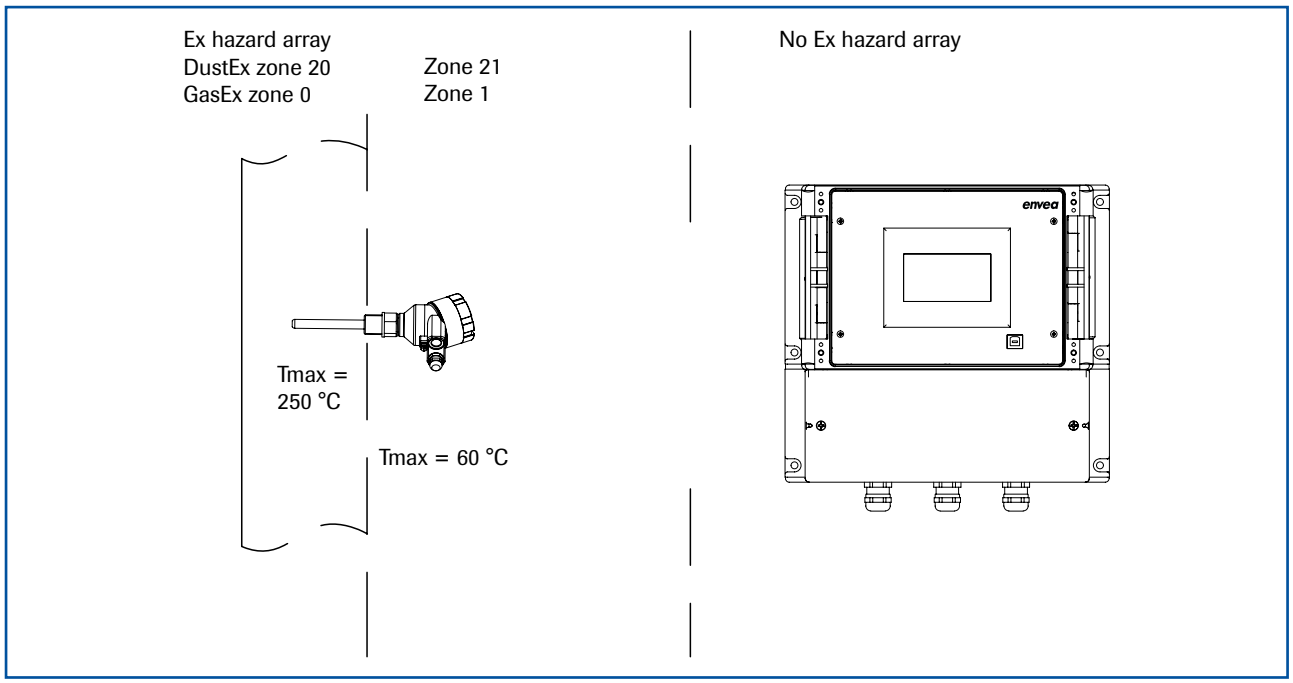
***-electronics / enclosure**

Zone 0: -20 °C ≤ $T_{process}$ ≤ 250 °C

Zone 1: -20 °C ≤ T_{amb} ≤ 60 °C

The sensor is not allowed to be used in areas of class IIC, in case of expected, intense charging processes.

- Equipment group: 2
- Equipment category: 1/2 Electrode zone 0 / enclosure zone 1
- For explosive mixtures of air and combustible dusts
- IP-code 68
- Permitted process temperature -20 to 250 °C
- Up to process temperatures of 130 °C, the sensor corresponds to temperature class T4. At process temperatures up to 195 °C, the sensor corresponds to temperature class T3 and at process temperatures up to 250 °C, the sensor corresponds to temperature class T2.



5. Electrical connection

5.1 Terrminal layout MSE 300-DR

1 Current output - 4 ... 20 mA	2 Current output + 4 ... 20 mA	3 Input Power supply 0 V DC	4 Input Power supply + 24 V DC
5 Not used	6 Alarm relay NC (break contact)	7 Alarm relay C	8 Alarm relay NO (make contact)

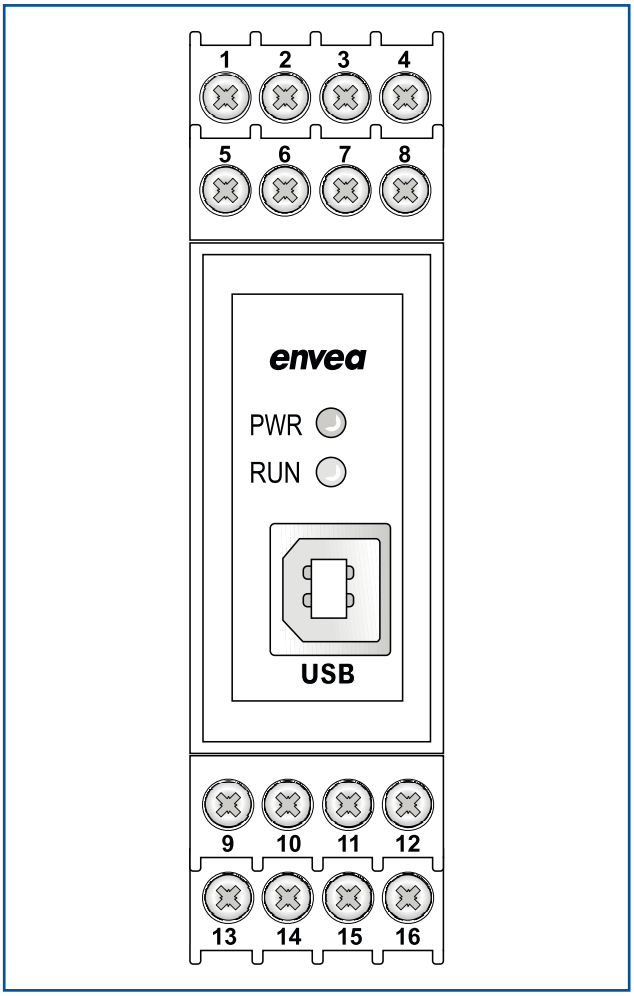


Fig. 14: Electrical connection of the MSE 300-DR

9 Digital pulse output (-)	10 Digital pulse output (+)	11 RS 485 Interface Data B	12 RS 485 Interface Data A
13 Sensor connection Cable 4 RS 485 Data B	14 Sensor connection Cable 3 RS 485 Data A	15 Sensor connection Cable 2 Power supply 0 V	16 **Sensor connection Cable 1 Power supply + 24 V**

5.2 Terminal layout MSE 300-FH

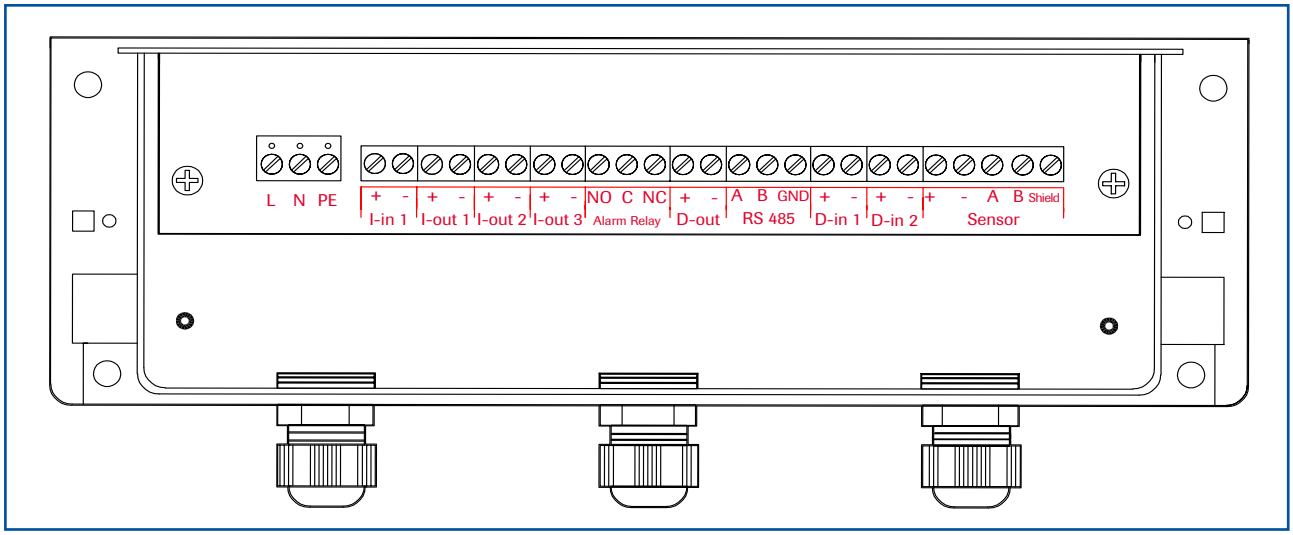


Fig. 15: Electrical connection of the MSE 300-FH

Evaluation unit			
Terminal No.		**Connection**	
Power supply connection			
L / +24 V		Input power supply 230 V / 50 Hz, 110 V / 60 Hz (optional 24 V DC)	
N / 0 V		Input power supply 230 V / 50 Hz, 110 V / 60 Hz (optional 24 V DC)	
PE		Earth	
Connections			
I-in1	+	Current input +	
	-	Current input -	
I-out1	+	Current output +	
	-	Current output -	
	Na	Not used	
	Na	Not used	
	Na	Not used	
	Na	Not used	
Min. / Max.- Relay	NO	Floating change-over contact NO (make contact)	
	C	Floating change-over contact C (common conductor)	
	NC	Floating change-over contact NC (break contact)	
D-out	+	Digital pulse output +	
	-	Digital pulse output -	
RS 485	A	RS 485 interface data A	
	B	RS 485 interface data B	
	GND	RS 485 interface ground	
D-in1	+	Digital interface 1 (+)	
	-	Digital interface 1 (-)	
D-in2	+	Digital interface 2 (+)	
	-	Digital interface 2 (-)	
Sensor	+	Power supply + 24 V	Cable no. 1
	GND	Power supply 0 V	Cable no. 2
	A	RS 485 data A	Cable no. 3
	B	RS 485 data B	Cable no. 4
	Shield	Shield	

5.3 Terminal layout C-Boxes

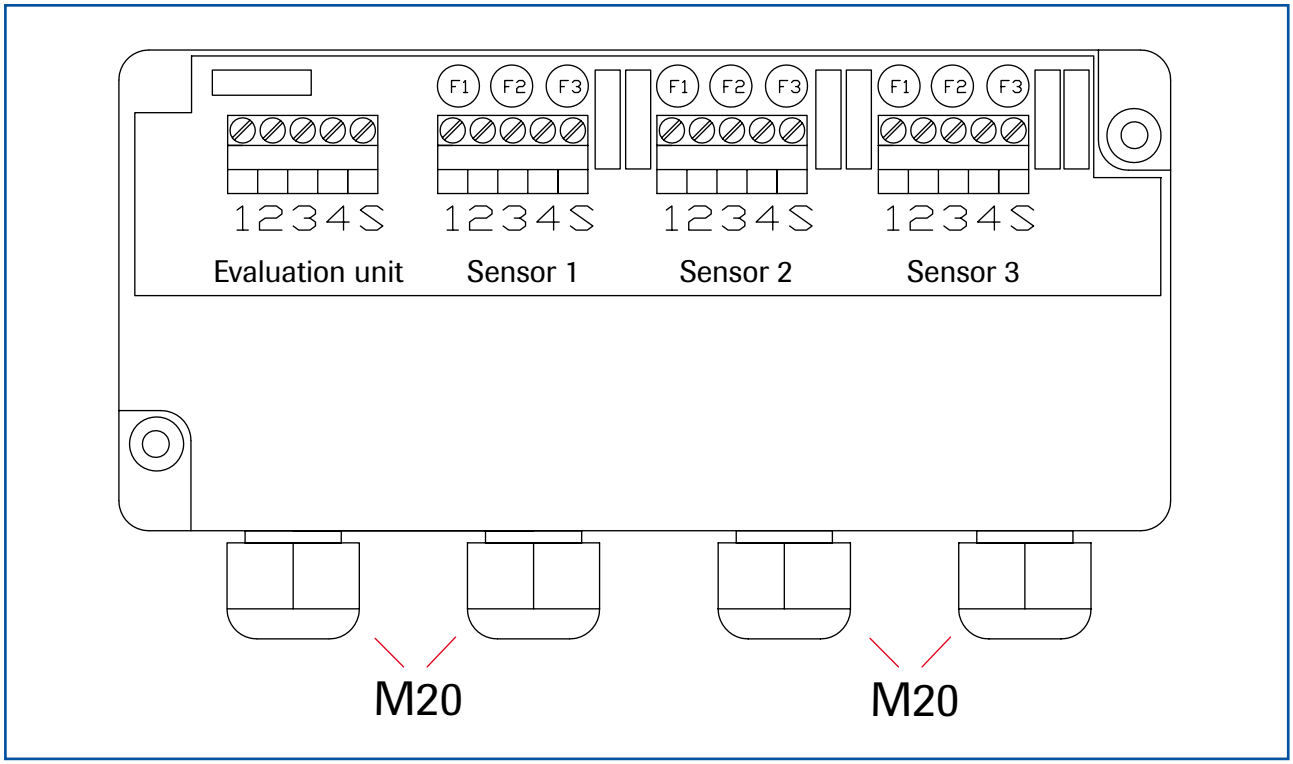
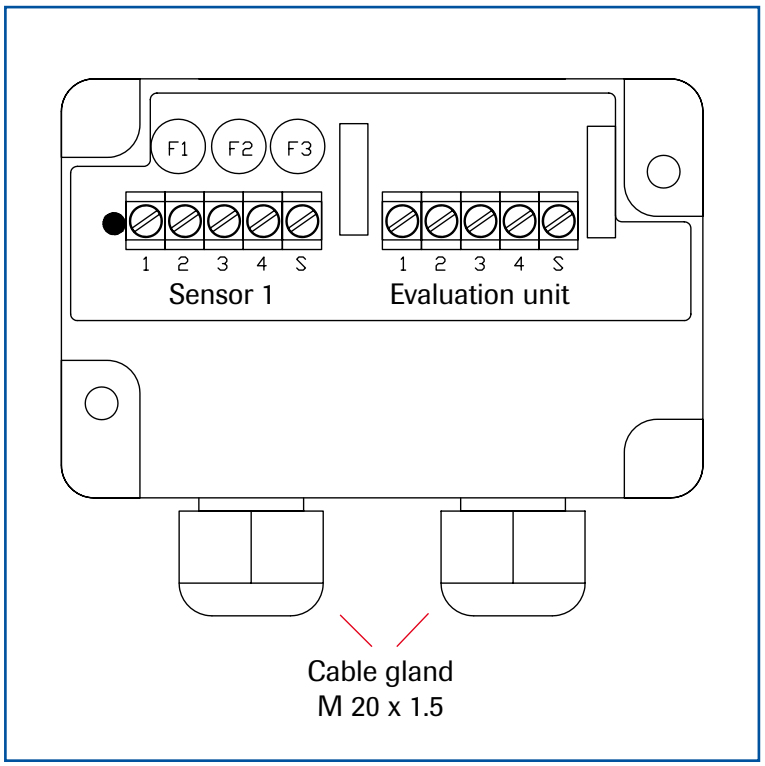


Fig. 16: Electrical connection for the C3-Box



Sensor 1 / 2 / 3

1 **Power supply + 24 V**
2 **Power supply 0 V**
3 RS 485, Data A
4 RS 485, Data B
S Shield

Evaluation unit

1 **Power supply + 24 V**
2 **Power supply 0 V**
3 RS 485, Data A
4 RS 485, Data B
S Shield

Fig. 17: Electrical connection for the C1-Box

6. Operator interface

The evaluation unit is a multi-sensor evaluation unit. So it is strongly recommended to check before commissioning whether the correct sensor is selected under menu item **System**.

The operator interface differs depending on the system design:

- DIN Rail housing without touchscreen, operation via PC software
- Field housing with display, alternative operation via PC software
- One to three sensor system

In the following, the basic operation of the PicoFlow system will be described as a one sensor system without re-entering the differences between the various variants.

6.1 Differences between the DIN Rail and field housing Evaluation unit

The MSE 300 in the DIN Rail housing is only a part of the functions available in the field housing.
The following overview clarifies the differences between the two versions.

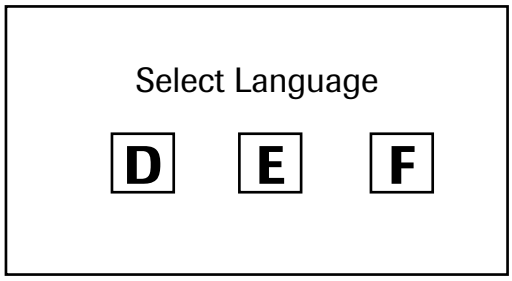
Function	Field housing	DIN Rail
Menu system		
• via PC software	yes	yes
• via display	yes	no
Measurement value display current output	yes	yes
Pulse Output for control of solenoid valves or for totaliser output	yes	yes
Alarm system relay output	yes	yes
Remote control digital input	yes	no
Autocorrect analogue input	yes	no
Totaliser display		
• via PC software	yes	yes
• via display	yes	no
Error output		
• on current output	yes	yes
• at relay	yes	yes
• via PC software	yes	yes
• via display	yes	no
• on status LED	no	yes

The evaluation unit in the DIN Rail can only be configured via an USB connection and a PC program. On the evaluation unit in the field housing, all functions can be configured by menu via the touch-sensitive display. The field housing evaluation unit can also be configured by PC.

The menu items on the display and in the PC software are numbered uniformly so that they can be referred to later on.

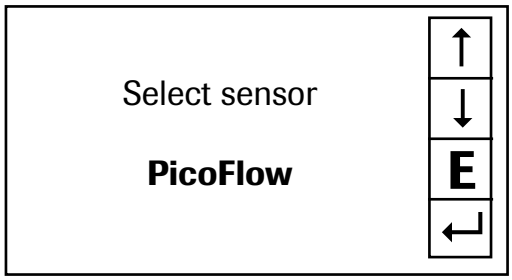
6.2 Display

The display is touch-sensitive. Available keys are displayed directly in context. When the measuring system is first started, a query is initiated to select the language and sensor. If no selection is made, the initialization disappears and the German language with a PicoFlow sensor is selected.



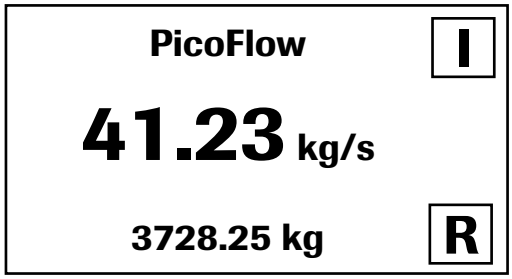
Initialization screen when the Evaluation unit in the field housing started first time.
Selection of the menu language:

Deutsch, **E**nglish, **F**rançais



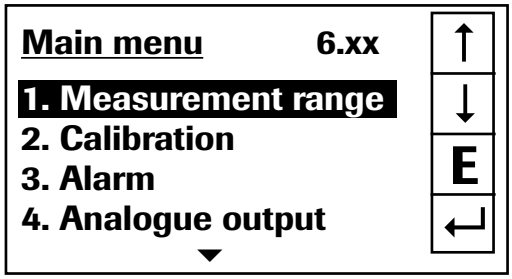
If a language has been selected, the sensor to be used must be selected.
To be available:
SolidFlow 2.0, Paddy, PicoFlow, MaxxFlow HTC, DensFlow, SpeedFlow 2.0, SlideControl 2.0, ProSens, M-Sens 2, M-Sens 3, M-Sens WR.

Afterwards the start page appears.



The start page display the following values:

- Tag No “PicoFlow“, freely selectable text which describes the material or the measuring point
- Measurement, here in [kg/s]
- Totaliser value since the last totaliser reset, here in [kg]
- [I] key for info
- [R] key for totaliser reset



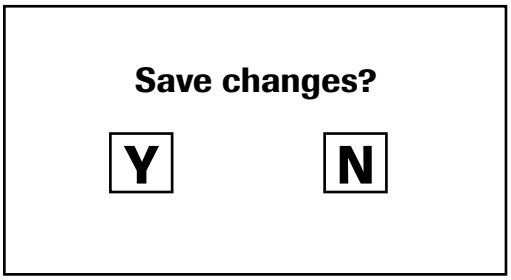
To access the menus, press and hold any area of the display for several seconds.
The sub-menu selection will be displayed:

In the menus and input fields, the displayed keys can be used to browse, select, edit or reject:

- Arrow: Scroll down the page, Select an option, Select a position in the input text
- [E] for ESC: Interrupt the function without making any changes
- [↵]: Select the function or confirm the input
- [C] for Clear: Delete a symbol or number.

Sensor Status			
	Temp	Raw value	Stat
S1	---	0.000123	OK
S2	---	0.000213	OK
S3	---	0.000321	OK
Average		0.000219	
		3728.25 kg	

With the key [I] you can choose between different information windows. The first window shows the raw values, temperature and the status of the sensor.
The second window displays the error memory.
Recent error codes always come first. If an error code is repeated, it will appear first, but will not be listed multiple times.



If any data has been changed, the change will only be taken into account when you exit the complete menu structure and answer [Yes] when asked if you wish to save the changes.

For reasons of simplicity, a further display menu screen has been dispensed with.
The display screens are directly derived from the menu structure in section 6.5.

Protection against unauthorised use:

If a password has been entered in menu **8. System** in **8.6 Password**, which is different to the “0000” default setting, you will be asked to enter a password when attempting to access the menus.
After the password has been successfully entered, the menus will be unlocked for approx. 5 minutes (from the last menu entry).

6.3 PC interface

Communication with a laptop or PC is carried out on the DIN Rail as in the field housing version optionally on the terminals via an RS 485 or on the front side via a USB interface.

✔ The **RS 485 connection** is attached to the evaluation unit in the field housing at the ModBus A (+) and ModBus B (-) terminals on the DIN Rail version, these connections are nos. 12 and 11, accordingly.
RS 485 is a bus connection; the ModBus address and the baud rate can be set on the device. Upon delivery, the communication parameters are set to:

- ModBus address 1
- Baud rate 9600, 8, E,1

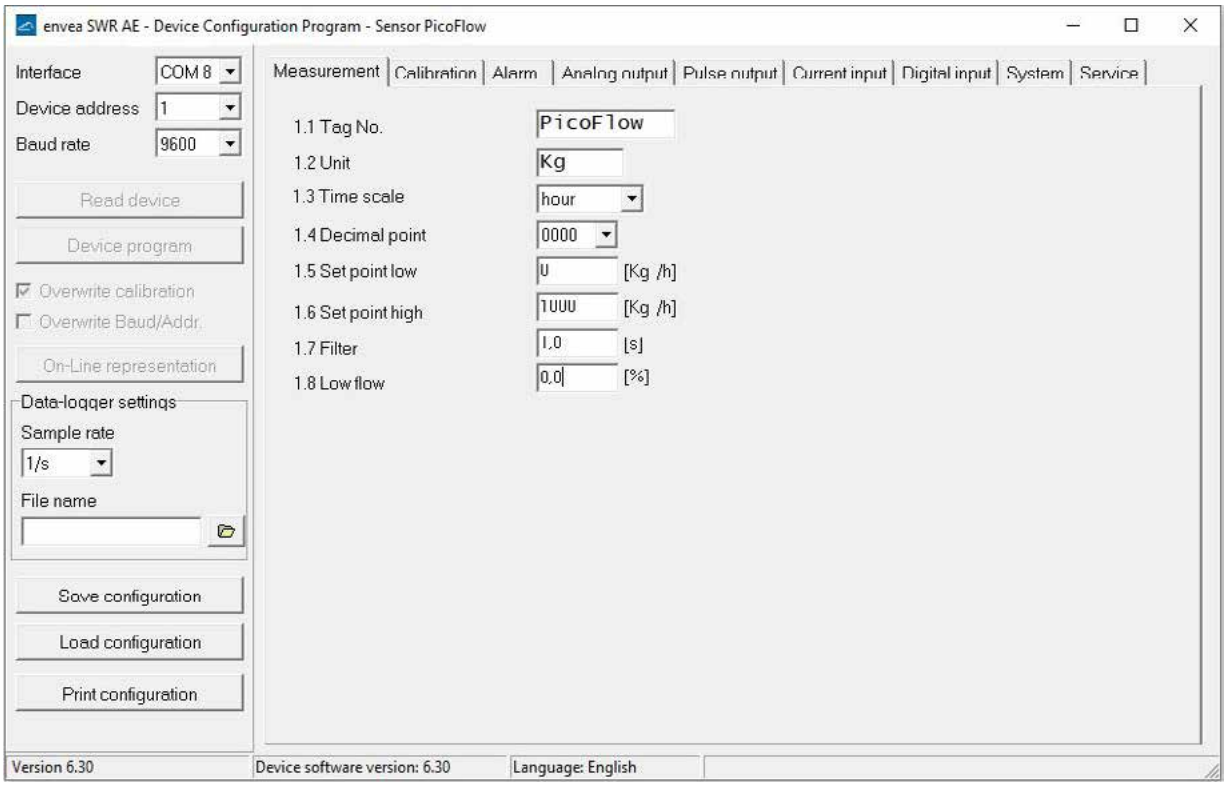
An RS 485 to USB adapter can be purchased from ENVEA Process.

✔ For the USB connection to the DIN Rail version is a standard USB-A-B cable included. The USB connection is a point-to-point connection that is not BUS-capable. The ModBus address and the baud rate for the front-side connections cannot be changed and are always:

- ModBus address 1 (or the device answers to all addresses)
- Baud rate 9600, 8, E,1

  When connected to the PC for the first time, any interface drivers enclosed with the evaluation unit must be installed.

After starting the software, the communication parameters must first be entered accordingly. These can be found in the top left of the program window. The COM port to be set is displayed in the device manager.



Communication is established by clicking on “Read device”. The acknowledgement message “Parameter read in” is displayed. If an error message is displayed instead, check the communication parameters and cable connections between the PC and the evaluation unit.

The edited data is transmitted to the evaluation unit via “Device program”.
Critical data concerning the ModBus communication and the calibration must be confirmed before the parameters are transmitted to the evaluation unit:

✔ If, when saving the the parameters in the evaluation unit, the system calibration data is changed, this action must be confirmed by checking “Overwrite calibration”.

✔ If, when saving the the parameters in the evaluation unit, the system interface parameters are changed, this must be confirmed by checking the selection “Overwrite baud/addr.”.

In addition, with the PC software,

- the evaluation unit parameters can be saved in a file (save configuration)
- the evaluation unit parameters can be loaded from a file (load configuration)
- the evaluation unit parameter can be printed via the windows standard printer (print configuration)
- the measured values can be logged in a data logger file (enter the file name and storage rate, and activate the data logger in the On-Line representation)

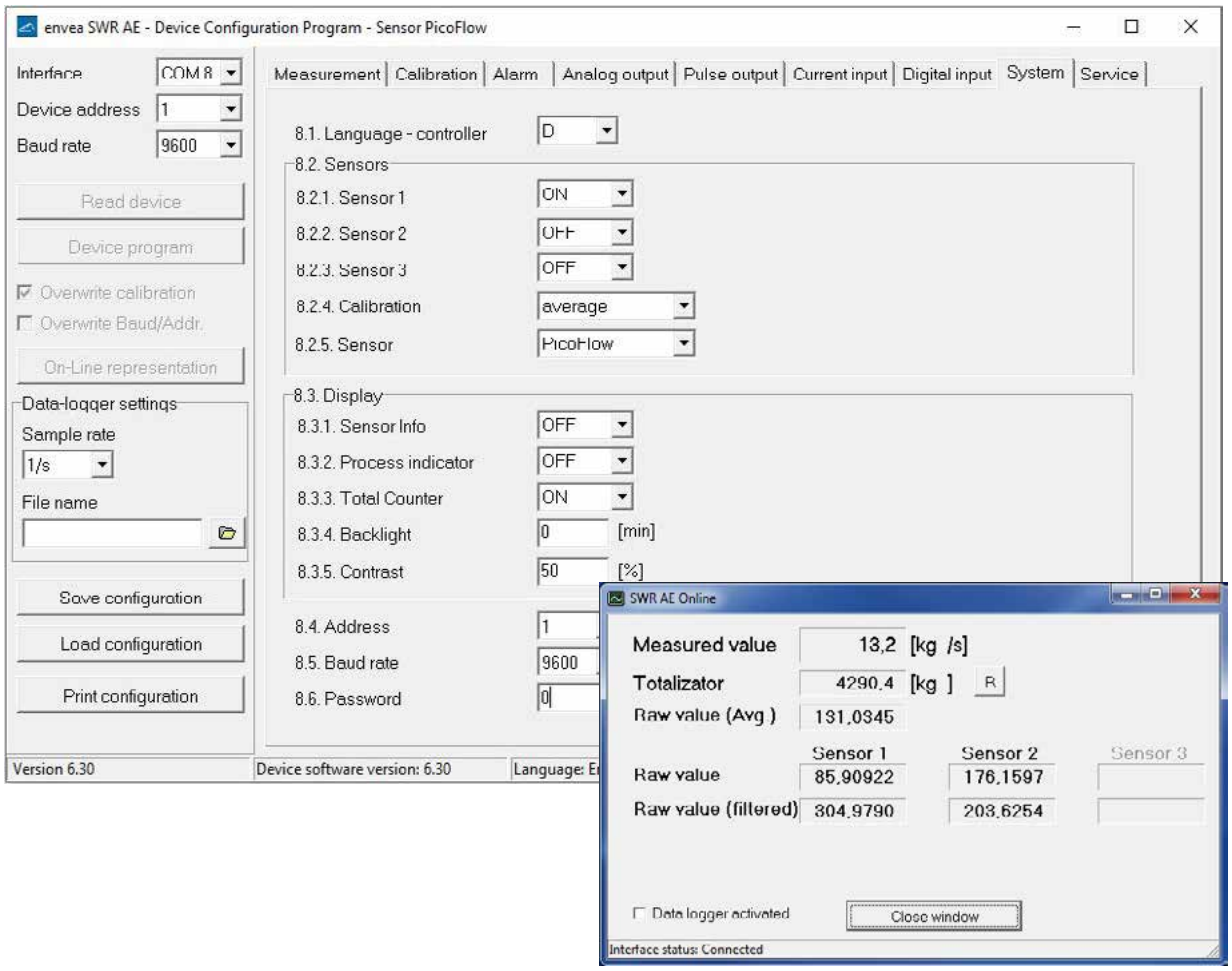
The software language can be set by right-clicking the “Sprache/Language/Langue” field in the bottom program line on “Deutsch/English/Français”.

Protection against unauthorised use:
The PC interface does not have a password prompt as it is assumed that only authorised personnel will have access to the PC and the software. However, the password to operate the display can be read and changed in menu **8. System** in **8.6 Password**.

6.4 One or more sensor systems

Up to three sensors can be connected to a evaluation unit if, for example, a larger flow section needs to be illuminated. In the evaluation unit, the corresponding number of sensors will then be registered and a joint average value will be calculated from their measurements.

The sensors are registered in menu **8. System**:



The multi-sensor function has no effect on the service and will not be explained in the following document.

If multiple sensors are used, this will only affect the application of sensors and the monitoring of sensors by the evaluation unit.

The presence of multiple sensors makes itself felt on the online-display and on the info area of the display.

For the construction of a multi-sensor system note the following:

- The sensors must be activated in the evaluation unit (Menu **8. System**, **8.2 Sensors**)
- Activated sensors are addressed by the evaluation unit on the sensor side, digital bus at the following addresses:
    - Address 1 – sensor 1
    - Address 2 – sensor 2
    - Address 3 – sensor 3

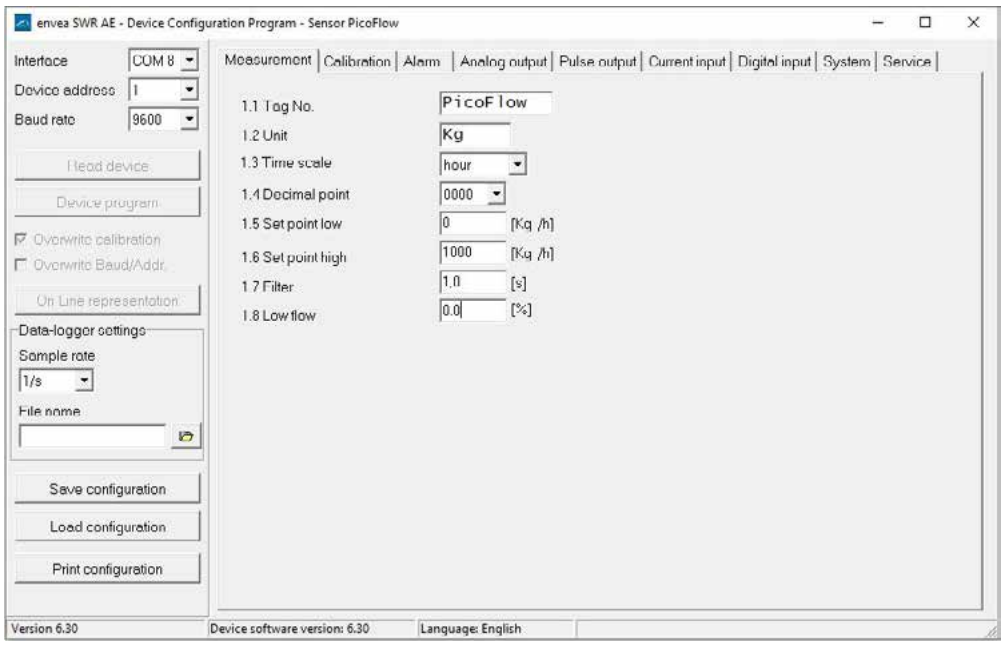
- With delivery of a multi-sensor system the sensors will be preconfigured on the addresses 1 – 2 – 3 and noted in the evaluation unit as active.
- Sensors and evaluation units, which are not preconfigured for a multi-sensor system always have address 1, only sensor 1 will be activated.
- Sensors which are inserted afterwards in a system must be adjusted by means of an separate service software to the required address.
- The correct address will be factory-preset when ordering spare parts with specified sensor number.

6.5 Menu structure

The menu structure supports the user when adjusting the measuring range, the calibration, the measurement values and the choice of additional functions. In this connection, the numbering both on the display and in the PC interface is identical:

1. Measuring range

Set all relevant measuring range settings



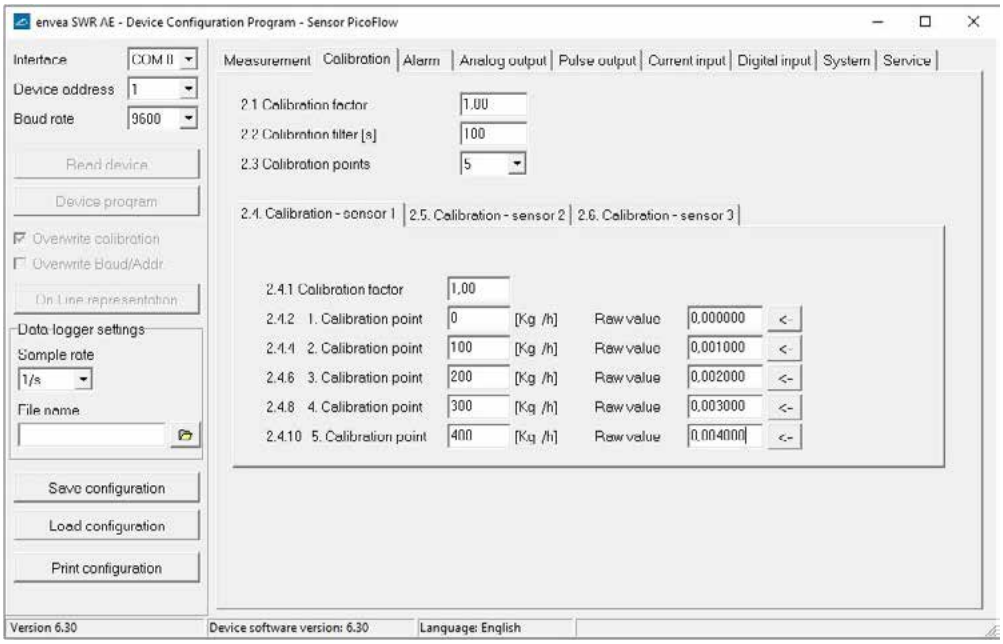
1.1 Tag No.	**Input:** free text (10 characters)	Name of the measurement point or product.
1.2 Unit	**Input:** unit text, e. g. kg	Required mass flow unit.
1.3 Time scale	**Selection:** hour / minute /second	Time base for the integration by the totaliser and the pulse output.
1.4 Decimal point	**Selection:** 0000, 0.000, 00.00, 000.0	Number representation and decimal point-accuracy in the measurement menu.
1.5 Set point low	**Input:** 0 … 9999	Throughput rates under this value will not be displayed at the current output. This does not concern the display indicator, totaliser or pulse output.
1.6 Set point high	**Input:** 0 … 9999	Throughput rates above this value will not be displayed at the current output. This does not concern the display indicator, totaliser or pulse output.
1.7 Filter	**Input:** 0.0 s … 999.9 s	Filtering of measurement for the indicator and the output values.
1.8 Low flow	**Input:** 0.0 % … 99.9 %	Throughput below this threshold are displayed as zero and are NOT totalised. Indication as % to measuring range end.

2. Calibration

Deposit a calibration curve
Depending on the selection under **8.2.4 Calibration**, the parameters to be entered are changing.

Average-Calibration
From the average value of all sensors, a common calibration table is created for throughput calculation.

2.1	Calibration factor	**Input:** 0.01 … 9.99	Factor for the subsequent adjustment of the actual measurement. All measurements are scaled by this factor.
2.2	Calibration filter [s]	**Input:** 1 … 9999	Filter time for recording the raw value during calibration. It would be made an average out of the measured RAW-values.
2.3	Calibration points	**Input:** 2 … 5	Number of support points for a linearisation above the operating range.
2.4	Calibration	**Calibration sub-menu**	
2.4.1	P1 value	**Input:** measurement	Output measurement in the selected mass/time unit.
2.4.2	P1 calibration	**Transfer:** raw value	Transfer of the current raw value (filtered) from the mass flow with the key [←]. The value can also be entered directly.
	. . . (depending on the number of support points)		For additional support points (depending on [2.3]), additional value pairs can be set.
2.4.n	Pn value	**Input:** measurement	
2.4.n	Pn calibration	**Transfer:** raw value	



Single calibration
Each sensor is assigned an individual calibration table. Afterwards, a throughput calculation takes place on the basis of the individual throughput values.

2.1	Calibration factor	**Input:** 0.01 … 9.99	Factor for the subsequent adjustment of the actual measurement. All measurements are scaled by this factor.
2.2	Calibration filter [s]	**Input:** 1 … 9999	Filter time for recording the raw value during calibration. It would be made an average out of the measured RAW-values.
2.3	Calibration points	**Input:** 2 … 5	Number of support points for a linearisation above the operating range.
2.4	Calibration	**Calibration sub-menu for sensor 1**	
2.4.1	Calibration factor	**Input:** 0.01 … 9.99	Factor for the subsequent adjustment of the actual measurement of sensor 1.
2.4.2	P1 value	**Input:** measurement	Output measurement in the selected mass/time unit.
2.4.3	P1 calibration	**Transfer:** raw value	Transfer of the current raw value (filtered) from the mass flow with the key [←]. The value can also be entered directly.
	. . . (depending on the number of support points)		For additional support points (depending on [2.3]), additional value pairs can be set.

2.5	Calibration	**Calibration sub-menu for sensor 2**	
2.5.1	Calibration factor	**Input:** 0.01 … 9.99	Factor for the subsequent adjustment of the actual measurement of sensor 2.
2.5.2	P1 value	**Input:** measurement	Output measurement in the selected mass/time unit.
2.5.3	P1 calibration	**Transfer:** raw value	Transfer of the current raw value (filtered) from the mass flow with the key [←]. The value can also be entered directly.
	. . . (depending on the number of support points)		For additional support points (depending on [2.3]), additional value pairs can be set.
2.6	Calibration	**Calibration sub-menu for sensor 3**	
2.6.1	Calibration factor	**Input:** 0.01 … 9.99	Factor for the subsequent adjustment of the actual measurement of sensor 3.
2.6.2	P1 value	**Input:** measurement	Output measurement in the selected mass/time unit.
2.6.3	P1 calibration	**Transfer:** raw value	Transfer of the current raw value (filtered) from the mass flow with the key [←]. The value can also be entered directly.
	. . . (depending on the number of support points)		For additional support points (depending on [2.3]), additional value pairs can be set.

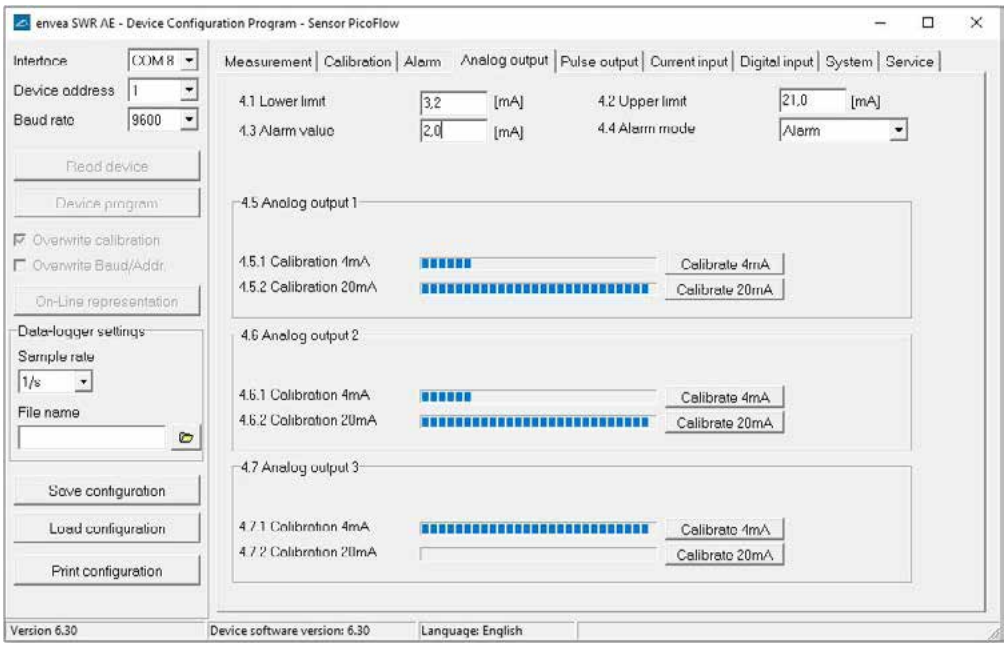
3. Alarm

Settings for relay contacts

3.1	Alarm type	**Selection:** Min/Max/none	The relay is operated if the measurement exceeds or falls below the max. limit or min. limit.
3.2	Alarm value	**Input:** 0 … 999.9	Limit value for monitoring min. or max.
3.3	Delay	**Input:** 0.1 … 99.9 s	The value must permanently exceed or fall below the set limit during this time.
3.4	Hysteresis	**Input:** 0.1 … 99.9 %	The alarm continues for as long as the measurement is not smaller or larger than the limit value plus or minus hysteresis.
3.5	Operation mode	**Selection:** NC / NO	**NC:** the relay is closed while there is no alarm. **NO:** the relay is closed, if there is an alarm.
3.6	Sensor alarm	**Selection:** OFF / ERR / PROC	**OFF:** Sensor errors or process indicators will not activate the relay. **ERR:** Serious sensor errors lead to an alarm on the relay. **PROC:** Fatal sensor errors and process indicators lead to an alarm on the relay. More information about the ERR and PROC signals, will be found in section error flags.

4. Analog output

Settings and calibration of analogue output



4.1	Lower limit	**Input:** 0 … 22 mA	Standard: 3.2 mA
4.2	Upper limit	**Input:** 0 … 22 mA	Standard: 21 mA
4.3	Alarm value	**Input:** 0 … 22 mA	Standard: 2 mA
4.4	Alarm mode	**Selection:** alarm / freeze	**Alarm:** Alarm value at output, during alarm measuring value is 0. **Freeze:** Last measurement value would be freeze on Analogue output, till the error is fixed.
4.5	Analogue output 1	**Submenu**	
4.5.1	Calibration 4 mA	**Selection:** set output current	The current output can be set via key functions and adjusted at the receiving end.
4.5.2	Calibration 20 mA	**Selection:** set output current	The current output can be set via key functions and adjusted at the receiving end.
4.6	Analogue output 2	**Submenu**	
4.6.1	Calibration 4 mA	**Selection:** set output current	The current output can be set via key functions and adjusted at the receiving end.
4.6.2	Calibration 20 mA	**Selection:** set output current	The current output can be set via key functions and adjusted at the receiving end.

4.7	Analogue output 3	**Submenu**	
4.7.1	Calibration 4 mA	**Selection:** set output current	The current output can be set via key functions and adjusted at the receiving end.
4.7.2	Calibration 20 mA	**Selection:** set output current	The current output can be set via key functions and adjusted at the receiving end.

The current output can be calibrated that the zero point (output of 4 mA) is applied to the background noise of the measuring point. If the noise level decreases due to process changes, material caking or other aging effects, less than 4 mA can be output at the analog output. In this way, a zero offset can be detected (zero point drift).
If this function is not required for process-technical reasons, the zero point must be set during calibration on a raw value of zero and / or the **4.1 Lower limit** must be set to 4 mA.
The PicoFlow gives only to analog output 1 a signal for the flow rate.

If the settings of the 4 mA or 20 mA signal are changed, the checkbox **Overwrite calibration** must be set.

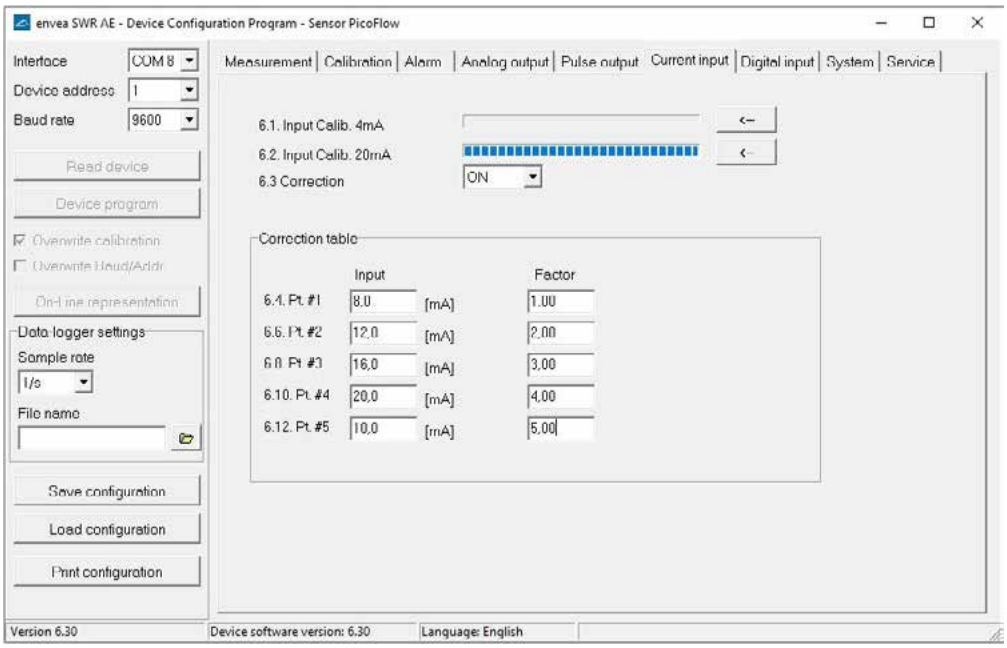
5. Pulse output

Passive signal for pulse cleaning or output of a totaliser

5.1	Function	**Selection:** none / cleaning / quantity	**None:** No pulse output **Cleaning:** Possibility to control a solenoid valve for compressed air-fluid. **5.4 Pulses/unit** without function. **Quantity:** The quantity is send as an impulse sequence to the output; Unit is like **1.2 Unit.** **5.2 Pulse period** and **5.3 Pulse length** without function.
5.2	Pulse period	**Input:** 1 s … 600 s	Time between two impulses
5.3	Pulse length	**Input:** 1 s … 60 s	Length of impulse
5.4	Pulses/unit	**Input:** 0.01 … 99.9	Number of pulses per unit

6. Analogue input

Possibility of autocorrection via external current signal.

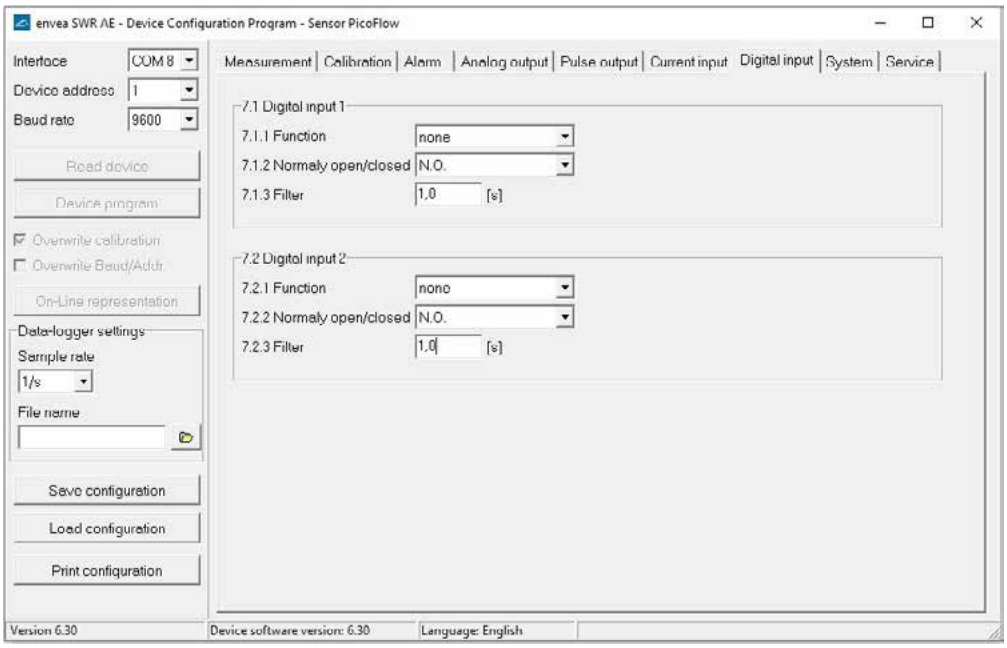


The connection of the current input is not galvanically isolated.
If the connection is incorrect, the CPU of the evaluation unit can be destroyed. An external galvanic isolation, by current disconnector or similar shall be provided.

6.1	Input calibration 4 mA	**Selection:** calibrate 4 mA input	The 4 mA signal must be read in via key function.
6.2	Input calibration 20 mA	**Selection:** calibrate 20 mA input	The 20 mA signal must be read in via key function.
6.3	Correction	**Selection:** ON / OFF	**ON:** Correction is activated. **OFF:** Correction is disabled.
6.4	P1-input	**Input:** 4 mA … 20 mA	Enter the current strength to be used for correction.
6.5	P1-factor	**Input:** 0.01 … 10	Factor for adjustment of the actual measured value.
6.n	Pn-input	**Input:** 4 m A … 20 mA	Possibility of further current values and correction factor.
6.n	Pn-factor	**Input:** 0.01 … 10	

7. Digital input

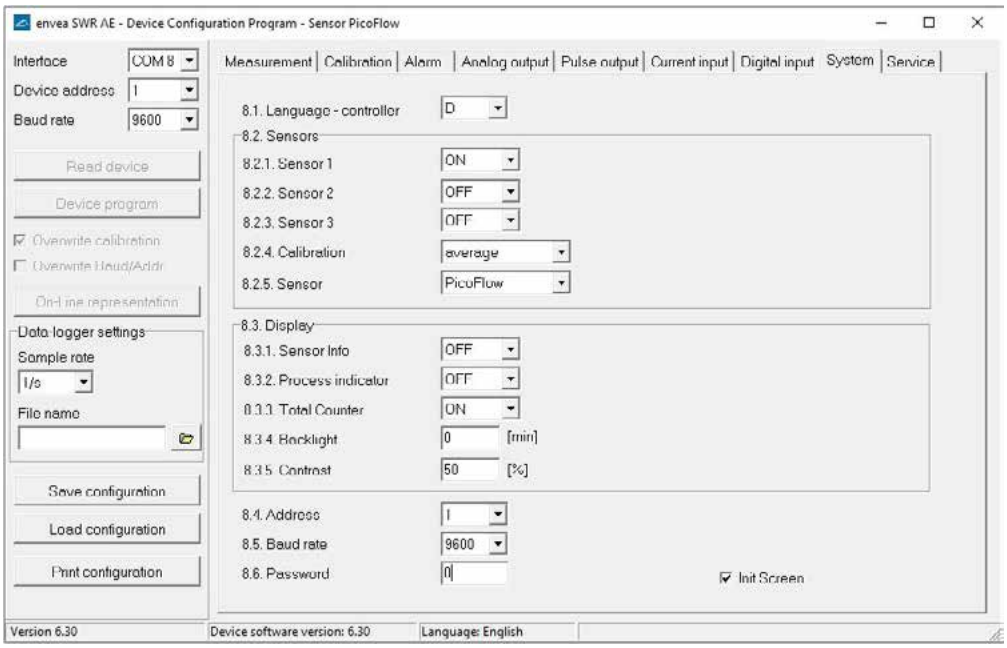
Selection of function for external control.



7.1	Digital input 1	**Submenu**	
7.1.1	Function	**Selection:** none / reset totaliser / AutoCal	**None:** digital imput disabled **Reset totaliser:** totaliser would be reset to zero **AutoCal:** an auto calibration will be start
7.1.2	Working direction	**Selection:** NO / NC	If necessary, invert the value of the input level.
7.1.3	Filter	**Input:** 0.1 … 99.9 s	Time during which the requested signal must remain pending.
7.2	Digital input 2	**Same as digital input 1**	

8. System

Basic adjustment of the system and evaluation unit

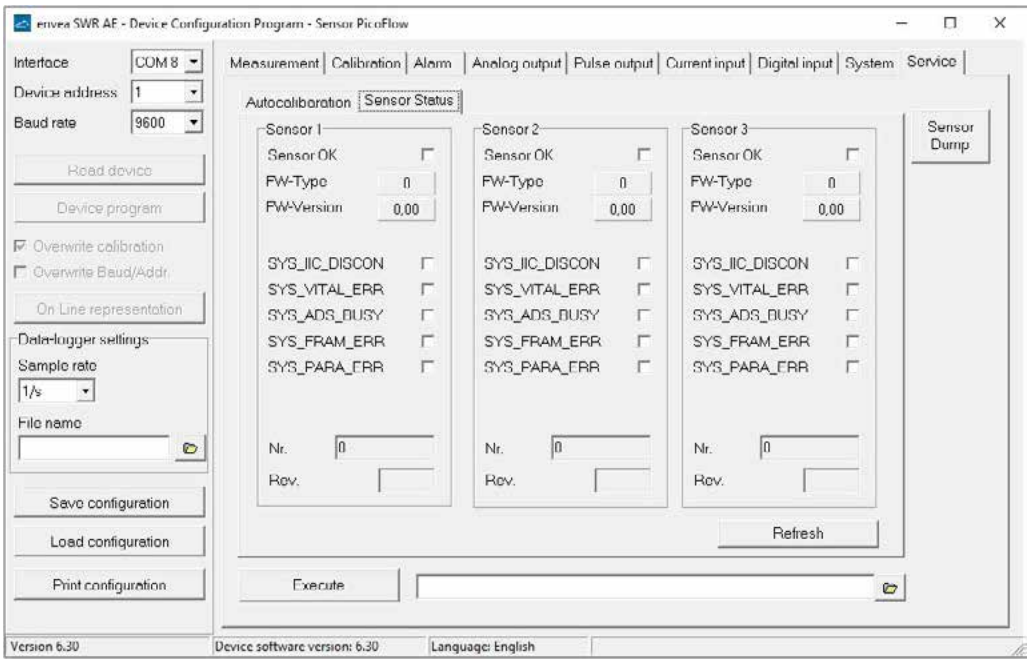


8.1	Language	**Selection:** D / E / F	Language on the evaluation unit
8.2	Sensors	**Sensor function and calibration**	
8.2.1	Sensor 1	**Selection:** ON / OFF	**ON**: Sensor is evaluated **OFF**: Sensor is ignored
8.2.2	Sensor 2	**Selection:** ON / OFF	**ON**: Sensor is evaluated **OFF**: Sensor is ignored
8.2.3	Sensor 3	**Selection:** ON / OFF	**ON**: Sensor is evaluated **OFF**: Sensor is ignored
8.2.4	Calibration	**Selection:** single / average	**This function is used only for multi-sensor systems!** **Single:** Calibration of single sensors: Each sensor is converted via an individual calibration table from the raw value to the throughput, after that the calculation of average throughput on the throughput values of the individual sensors is taking place. **(This function should only be used by trained personnel of ENVEA Process.)** **Average:** Calibration by the average value from raw values: The throughput will be calculated with a common calibration table after forming the average from raw values.

8.2.5	Sensor	**Selection:** SolidFlow 2.0 / Paddy / PicoFlow / MaxxFlow HTC / DensFlow / SpeedFlow 2.0 / SlideControl 2.0 / ProSens / M-Sens 2 / M-Sens 3 / M-Sens WR	The evaluation unit verifies the availability of registered sensors on the selected type, calculates the measurement values on this basis and signals if necessary corresponding errors. Incorrect sensor selection leads to a refusal to communicate.
8.3.	Display		
8.3.1	Sensor info	**Selection:** ON / OFF	**ON:** show info key on display **OFF:** hide info key
8.3.2	Process indicator	**Selection:** ON / OFF	**ON:** Process indicators will be shown on display and via double blink on the DIN Rail. **OFF:** Process indicators will not be shown.
8.3.3	Totalisator	**Selection:** ON / OFF	**ON:** Totalisator will be shown on display. **OFF:** Totalisator will be hide.
8.3.4	Backlight	**Input:** 0 … 99 min	Lighting of the Display in minutes 0 = permanent lighting 99 = time selection for lighting
8.3.5	Contrast	**Input:** 0 … 100 %	In the case of display exchange, the contrast can be changed via the PC software, if necessary.
8.4	Address	**Input:** 1… 255	ModBus address of evaluation unit, if operated on a PLC or PC as a slave.
8.5	Baud rate	**Selection:** 4800/9600/19200/ 38400 baud	Communication speed of the evaluation unit when this is operated as a ModBus slave on a PLC or a PC.
8.6	Password	**Input:** 0… 9999	0000 = No password XXXX = Four-digit password, which is queried when the menu is called up on the display. Automatic lock five minutes after the last display input.

9. Service

Display on the sensor status



The status of each connected sensor is displayed in menu **9. Service**. FW type, FW version, temperature, serial number and possible hardware errors are automatically read and displayed. In the case of a display exchange, the contrast could be changed via the PC software.

Only according to instructions from personnel of ENVEA Process:

If a detailed error analysis is necessary, a copy of all ModBus registers can be stored as a text file in the installation folder of the software by clicking on the **sensor dump**. This is only possible with the PC software. In addition, a software with deeper access to the sensors can be started via the PC software.

On the touchscreen only the information of the individual sensor will be shown.

7. Start-up procedure

7.1 Basic start-up

Upon delivery, the sensor is not calibrated to the product to be measured and must be parameterised when started up. During the process, the mass flows measured by the sensor will be assigned to the display values and output quantities required by the user.

The following points must first be checked:

- Correct position and proper installation of the sensor in the transport line.
- The correct connection between the sensor and the evaluation unit.
- A warm-up time of approx. 5 minutes before starting calibration and after switching on the sensor's power supply.

At the beginning of the calibration, it must be checked whether the correct sensor is selected under the menu item **System**. If the correct sensor has been selected, the desired measuring range and the physical unit can be entered under **1. Measurement**. The **1.2 Unit** is a free text, there are 10 characters available.
The calibration of the system is carried out on at least two calibration points in **2. Calibration.**

Min point	The first calibration point will be set at running process, but without any product. For calibration of this zero point it must be given a “0” on **2.4.1 Val. P1**, afterward the RAW value (**2.4.2 Calib. P1**) must be calibrate. The RAW value could be calibrated by reading the sensor directly or manually by calculate the RAW value over the datalogger in the software.
Working point	During normal conveyance, the second point will be set. The flow rate will type in **2.4.3 Val. P2** and the RAW value will be read direct under **2.4.4 Calib. P2** or could be calculate manually by using the datalogger in the software. The value can be corrected afterwards during weighing.

Once the calibration points have been saved, the transfer of the calibration parameters must be confirmed. On the evaluation unit in the field housing, this is done by a security query when leaving the menu structure. In the software it is mandatory to set the checkmark at **Overwrite calibration**. If the checkmark is set, the parameters will be transferred to the evaluation unit by clicking on **Device program**.

The device has thus performed its basic function and the measurements are displayed.

Additional support points	If non-linearities occur when measuring with different flow rates, up to 5 support points can be selected in **2.3 Calibration points.** These support points could be calibrated with different flow rates. If an average calibration is performed, the procedure only has to be carried out once. If a single calibration is carried out, the calibration procedure must be carried out individually for each connected sensor.

7.2 Datalogger function in the software

To determine the raw values via the Datalogger function of the PC software, a file path first must be stored. The file path and file name can be selected by clicking on the folder icon next to **File name**. If the file path is stored, the sample rate could still be changed, this is recommended for long recordings. For determining the raw values for a calibration point, the default setting of 1 (raw value) / second is recommended.

To start the datalogger, the **On-line representation** must be started. As soon as the checkbox on **Datalogger activated** is set in the on-line display, the recording starts and the log file is created in the background.

The data logger is only activated as long as the on-line display is open. If the window of the on-line display or the entire software is closed, the data recording is aborted without further notice.

For an evaluation of the recorded log file, it must be opened with Excel or a similar program.
The content of each column of the log file is named in the first line.

In order to determine the appropriate raw value for a calibration point, the mean value must be determined from the period of the reference extraction. The mean value can be calculated by Excel with the function *=AVERAGE ( )*. The calculated mean value of the raw value will be entered in the box next to the raw value in the configuration software.

In order to transmit the determined parameters to the evaluation unit, the check mark **Overwrite calibration** must be set .

7.3 Adjusting the measurement values

The system's additional functions can be set in the following menus:

Alarms	Values for flow rate lower or upper limits can be set in **3. Alarm.** A sensor monitoring alarm can also be activated here.
Analogue output	The assignment of the analogue output values takes place in **4. analogue output**. Upper and lower limit of the permitted current and the fault current are set here. The analogue output is an active signal. In the field housing version, analogue outputs 2 + 3 are provided for the MaxxFlow HTC. All other sensors provide their 4 ... 20 mA signal to analogue output 1.
Pulse output	Under **5. Pulse output** there is the possibility of using different impulses. A cleaning pulse can be used for a pneumatic cleaning on the sensor. For an external totaliser output there are impulses, which correspond to a specific conveyed mass. The pulse duration is 50 Hz, a faster query cannot be guaranteed. An internal totaliser function integrates the mass flow over time. The pulse output is an open collector and need an active power supply for pulsing.
Current input	Various input currents can be stored under **6. Current input**. When the current is applied, the corresponding correction factor is applied to the measured value. The input current also must be adjusted here.
Digital input	In **7. Digital input,** the system's digital inputs can be assigned various functions and their working direction.
System	In **8. System,** functions such as selection of the menu language, the number of connected sensors and their average, the display screen or ModBus addressing and speed are summarised.
Totaliser	The entire flow volume since the last totaliser reset can be read with the totaliser function. A reset can be performed via an external control cable or directly via the display by pressing the R symbol.

8. Error signalling

For monitoring the availability a wide range of functions for self-diagnostics were integrated, in order to signal various errors:

1. **Fatal error (ERR):**
   Fatal errors (ERR) always set the current output to the set alarm value. Technical problems or problems with the complete system are displayed on the touchscreen. An ERR require every time a replacement or repair of a component:

- failure of the communication to a sensor (sensor failure)
- failure of a subcomponent of a sensor (temperature monitoring, heating control, memory, data consistency etc. on the sensor)
- inconsistency of signal paths in the sensor (the amplifier stages, DC offsets)

2. **Process indicators (PROC):**
   Process indicators (PROC) are merely a violation of the set parameters and are to be understood as information to improve the measuring process. Process indicators are not output at the current output, but can be displayed on the display (field housing) or the RUN LED (DIN Rail) as well as optionally on the relay:

- temperature instability in the sensor due to thermal stress from outside (over-temperature, low temperature)
- overload of the sensor caused by material flow (too much, too little)

Process indicators show if necessary temporary appearing oddities in the process, which can be avoided with a better adjustment of sensor parameters or conveying parameters. They thus deliver more an indication of potential for optimization at the measuring point.

Type of fault	Display (field housing)	Run-LED (DIN Rail)	Relay (optional)	Current output
No fault	Sensor status OK on the information display (Button [I])	Single flash every second	Normal state	4 ... 20 mA
PROC (process indicators)	Display with indicator code in the bottom display line; advanced information on key [I]	Double flash every second	Activated, when Relais-Alarm-Option PROC is chosen	4 ... 20 mA
ERR (fatal errors)	Display with error code in the bottom display line; advanced information on key [I]	Triple flash every second	Activated, when Relais-Alarm-Option PROC **or** ERR is chosen	2 mA (or for the current output adjusted, chosen alarm value)

Error codes: Error and indicator codes are composed of the letter E (ERR = error), P (PROC = process indicator) and a three-digit hexadecimal value from “000” to “FFF”. From the displayed code the cause can be investigated.

Time Out error: In order not to complicate the start up of a process plant by process- or heating status errors, non fatal errors will be signalled only after a period of about 5 minutes after a reset of the measuring system at the outputs. The time-out period is visible in a small “t” in the left upper corner of the display (field housing only).

8.1 Compatibility

For the PicoFlow system two different software versions for the evaluation unit and associated PC software are available.

Technical innovations have caused a supplement of new functions, so that only the corresponding versions can be used together on evaluation unit and PC:

Sensor	Evaluation unit (field housing or DIN Rail)	PC software
All PicoFlow		
	All evaluation unit with FW.5.xx	Version till V 5.04
	All evaluation unit with FW.6.xx	Version from V 6.01

8.2 History of versions

FW V.5.03:

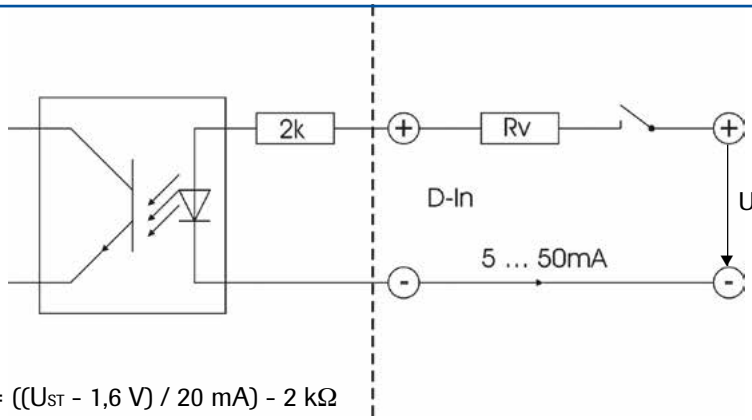
- full function release for evaluation unit and PC

FW V.6.xx

- improvement of error monitoring (ERR, PROC)
- change from fixed point to floating-point values in the calibration table
- introduction of further products
- zero drift detection for the current output
- error-timeout for the reset
- current input for auto correction
- pulse output for control of solenoid valves for pneumatic cleaning
- possibility to calibrate a low flow

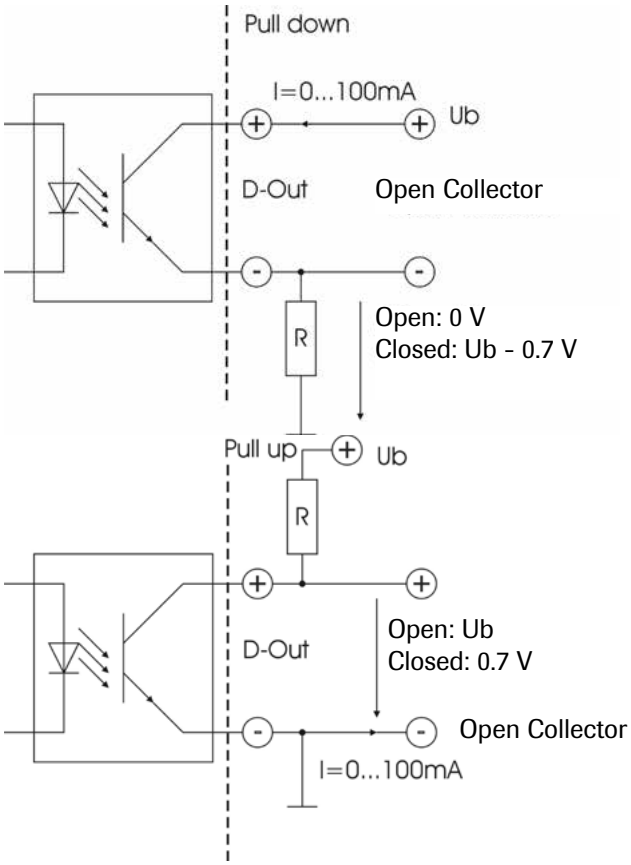
9. Connection examples

9.1 Digital input



$R_V = ((U_{ST} - 1{,}6\ V) / 20\ mA) - 2\ k\Omega$

9.2 Impulse output



R = (Ub - 0,7 V)/I

10. Maintenance

Warning!

- Switch off the power supply for all maintenance or repair works on the measuring system. The tube must not be in operation during a sensor exchange.
- Repair and maintenance work must be carried out by trained or expert personnel only.
- The system is maintenance-free.

11. Warranty

Warranty is granted for one year starting from delivery date under the condition that the operating instructions have been followed, no interventions on the appliances have been made and the components of the system show no mechanical damage or wear resistance.

In case of a defect during the warranty period, defective components are repaired or are replaced free of charge. Replaced parts turn into the property of ENVEA Process. If desired by the costumer that the parts should be repaired or replaced in its factory, then the costumer has to take over the costs for the ENVEA Process-service staff.

ENVEA Process is not responsible for damage, which did not develop at the delivery article; especially ENVEA Process is not responsible for escaped profit or other financial damages of the customer.

12. Troubleshooting

- **Warning!**
  The electrical installation must only be checked by expert personnel.

Problem	Cause	Measure
Measuring system does not work. POW LED off. RUN LED off.	Power supply interrupted.	Check the power supply.
	Break of cable.	Check the connecting cables for a possible break of a cable.
	Fuse defective.	Exchange the fuse.
	Device defective.	Please call ENVEA Process for further instructions.
Measuring system does not work. POW LED on. RUN LED off.	Microprocessor does not start.	Power supply switch off and switch on. Program cables remove.
Measuring system works. POW LED on. RUNLED flashes three times each cycle.	No sensor communication.	Sensor damaged. Cable break between sensor and measuring system.
	Sensor wrong connected.	Check cable.
	Sensor damaged.	Replace sensor.
	No 24 Volt supply on sensor.	Assure power supply.
	Voltage drop on the supply line too highly.	Examine cable lengths.
Measuring system outputs wrong values.	Calibration not correct.	New calibration.
	Calibration shifted by abrasion on front end of sensor.	New calibration.
Relay output - Relay flickering.	Hysteresis too small.	Increase hysteresis, check effects caused by external devices.
Do not open, as otherwise the warranty claim expires!		

12.1 Error codes

Type	Display	DIN Rail flashing	Current output	Cause	Action
ERR	DISC	3	2 mA	Wrong sensor connection, wrong sensor or sensor would not detect.	Poof of cabling, voltage, earthing and software parameter.
ERR	ID	3	2 mA	Sensor respond with wrong ID.	Check if the correct sensor is chosen in the menu.
ERR	E001	3	2 mA	Defective internal amplifier (DC Offset).	Turn power off / on. If not helpfully sensor exchange.
ERR	E002	3	2 mA	Defective data bus.	Turn power off / on. If not helpfully sensor exchange.
ERR	E004	3	2 mA	Caking between antenna and housing.	Clean sensor.
ERR	E010	3	2 mA	Defective converter.	Turn power off / on. If not helpfully sensor exchange.
ERR	E080	3	2 mA	Defective parameter memory.	Turn power off / on. If not helpfully sensor exchange.
ERR	E100	3	2 mA	Parameter table not readable.	Turn power off / on. If not helpfully sensor exchange.

A detailed error description and following troubleshooting can be carried out by trained ENVEA Process technicians.

13. Technical Data

Sensor / Sensor accommodation	
Housing	Aluminium
Protection category	IP66
Operating temperature	-20 ... + 60 °C (max. 150 °C)
Max. working pressure	10 bar
Weight	1.5 kg
Sensor rod	Material: ceramic protected stainless steel; max. 450 mm
Accuracy	± 5 % in calibrated range
Evaluation unit MSE 300-FH	
Power supply	110 / 230 V AC 50 Hz (optional 24 V DC)
Power consumption	20 W / 24 VA
Protection category	IP65 to EN 60 529/10.91
Ambient operating temperature	-10 ... +45 °C
Dimensions	258 x 237 x 174 mm (W x H x D)
Weight	Approx. 2.5 kg
Interface	RS 485 (ModBus RTU) / USB
Cable screw connectors	3 x M20 (4.5 - 13 mm Ø)
Connection terminals cable cross-section	0.2 – 2.5 mm² [AWG 24-14]
Current output	3 x 4 ... 20 mA (0 ... 20 mA), load < 500 Ω (Active)
Relay contact	Max. rated load: 250 V AC Max. peak current: 6 A Max. rated load 230 V AC: 250 VA Max. breaking capacity DC1: 3/110/220 V: 3/0.35/0.2 A Min. swithing load: 500 mW (10 V/5 mA)
Data backup	Flash memory
Pulse output	Open Collector - Max. 30 V, 20 mA
Evaluation unit MSE 300-DR	
Power supply	24 V DC ± 10 %
Power consumption	20 W / 24 VA
Protection type	IP40 to EN 60 529
Ambient operating temperature	-10 ... +45 °C
Dimensions	23 x 90 x 118 (W x H x D)
Weight	Approx. 172 g
Interface	RS 485 (ModBus RTU) / USB
DIN Rail fastening	DIN 60715 TH35
Connection terminals cable cross-section	0.2 – 2.5 mm² [AWG 24-14]
Current output	1 x 4 ... 20 mA (0 ... 20 mA), load < 500 Ω (Active)
Relay contact	Max. rated load: 250 V AC Max. peak current: 6 A Max. rated load 230 V AC: 250 VA Max. breaking capacity DC1: 3/110/220 V: 3/0.35/0.2 A Min. swithing load: 500 mW (10 V/5 mA)
Data backup	Flash memory
Pulse output	Open Collector - Max. 30 V, 20 mA

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